

Designing of an Analog Sallen Key Band Pass filter using Ant Colony Optimization

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Abstract:*In this project, an analog Sallen Key band-pass filter is designed and simulated. The filter is designed for the given specifications of center frequency of 15 kHz. The architecture that will be used is the Sallen-Key. Analog filters depend upon the values of discrete components (Resistors and Capacitors) which are selected from the series following constant values chosen. It is very exhaustive to search on all possible combinations of value choices for an optimized design. Several Optimization techniques like Ant Colony Optimization have proved a capacity to treat such problem effectively. In this work, Ant Colony Optimization (ACO) technique is applied to the Second Order Sallen Key Band Pass Filter Design. MATLAB simulations are used to validate the obtained result/performances.*

Keywords: Band-pass filter, Quality factor, Center Frequency, MATLAB

1 INTRODUCTION:

“A filter is a device that passes electric signals at certain frequencies or frequency ranges while preventing the passage of others”— Webster. Filters are widely used in variety of application like in the field of telecommunication, band-pass filters are used in the audio frequency range (0 kHz to 20 kHz) for modems and speech processing. High-frequency band-pass filters (several hundred MHz) are used for channel selection in telephone central offices. Data acquisition systems usually require anti-aliasing low-pass filters as well as low-pass noise filters in their preceding signal conditioning stages. System power supplies often use band-rejection filters to suppress the 60-Hz line frequency and high frequency transients. In addition, there are filters that do not filter any frequencies of a

complex input signal, but just add a linear phase shift to each frequency component, thus contributing to a constant time delay. These are called all-pass filters. At high frequencies (> 1 MHz), all of these filters usually consist of passive components such as inductors (L), resistors (R), and capacitors (C). They are then called LRC filters. In the lower frequency range (1 Hz to 1 MHz), however, the inductor value becomes very large and the inductor itself gets quite bulky, making economical production difficult. In these cases, active filters become important. Active filters are circuits that use an operational amplifier (op amp) as the active device in combination with some resistors and capacitors to provide an LRC-like filter performance at low frequencies. They are very much inexpensive in comparison to passive filters due to variety of cheaper op-amp and absence of costly inductors. In this paper, an analog Sallen Key Band Pass filter is designed using Ant Colony Optimization.

2.1 ANT COLONY OPTIMIZATION:

Ant colony algorithm is the probabilistic technique to compute the computational problem. This algorithm is based on the food finding technique of ant. Ant is seeking for path between their colony and food so ant searching for the food and search which food is nearer to their colony then establish shortest path between colony and food.

With the help of pheromones trail, the inspiring source of ACO is the foraging behavior of real ants.

2.2 The Double Bridge Experiment:

The ants begin by walking randomly. They cannot see the ground and have a very limited view of what is around them.

Therefore, if the ground has not been explored yet, they will just wander and take random decision at each crossroads.

After a while, the places around the nest will be all explored. The ants will get to know that by the marking done by the previous ants. Indeed, they will leave behind them the famous pheromones and inform the other ants that the way is already explored.

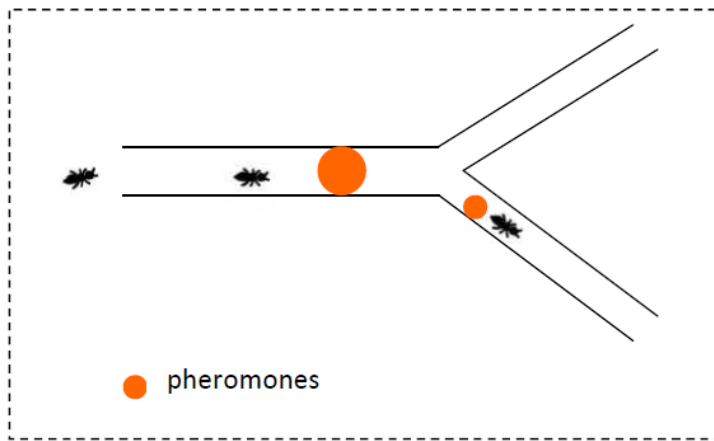


Fig.1: Ants & Pheromones [11]

The concentration of pheromones depends on the number of ants who took the way, the more ants taking the way, the more pheromones. The configuration is as shown in figure 1: the nest of a colony of ants is connected to the food via two bridges of the same length. In such a setting, ants start to explore the surroundings of the nest and eventually reach the food source. Along their path between food source and nest, ants deposit pheromones. Initially, each ant randomly chooses one of the two bridges. However, due to random fluctuations, after some time one of the two bridges presents a higher concentration of pheromones than the other and, therefore, attracts more ants. This brings a further amount of pheromone on that bridge making it more attractive with the result that after some time the whole colony converges toward the use of the same bridge.

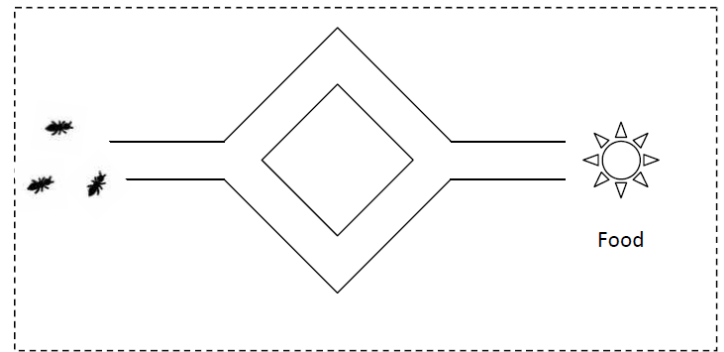


Fig.2: The Double Bridge Experiment [11]

The second experimentation, figure 2 gives also two paths to the food source, but one of them is twice longer than the other one. Here again the ants will start to move randomly and explore the ground. Probabilistically, 50% of the ants will take the short way while the 50% others will take the long way, as they have no clue about the ground configuration

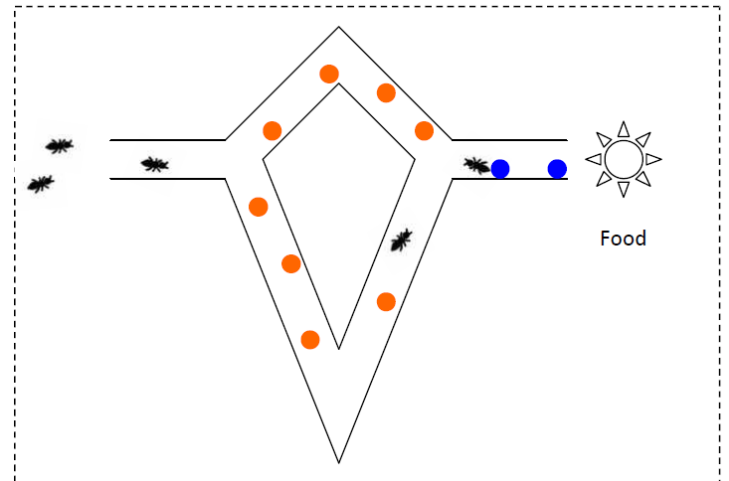


Fig.3: Ants coming back to the nest [11]

The ants taking the shorter path will reach the food source before the others, and leave behind them the trail of pheromones. After reaching the food, they will turn back and try to find the nest. At the cross, one of the paths will contain pheromones although the other one will be not explored. Hence the ant which carries the food will take the path already explored, as it means it is the way to the nest. As the ant is choosing the shortest way and will continue to deposit

pheromones, the path will therefore become more attractive for others. The ants who took the long way will have more probability to come back using the shortest way, and after some time, they will all converge toward using it. Consequently, the ants will find the shortest path by themselves, without having a global view of the ground. By taking decision at each cross according to the pheromones amount, they will manage to explore, find the food, and bring it back to the nest, in an optimized way.

ACO was initially used to solve graph related problems, such as the traveling salesman problem (TSP), vehicle routing problem, For solving such problems, ants randomly select the vertex to be visited. When ant k is in vertex i , the probability of going to vertex j is given by expression (1)

$$\left\{ \begin{array}{ll} \frac{(\tau_{ij}) \cdot (\eta_{ij})^\beta}{\sum_{i \in J_i^k} (\tau_{il})^\alpha (\eta_{il})^\beta} & \text{if } j \in J_i^k \\ 0 & \text{if } j \notin J_i^k \end{array} \right\} \quad (1)$$

Where J_i^k is the set of neighbors of vertex i of the k^{th} ant, τ_{ij} is the amount of pheromone trail on edge (i, j) , α and β are weightings that control the pheromone trail and the visibility value, i.e. η_{ij} which expression is given by (2)

$$\eta_{ij} = \frac{1}{d_{ij}} \quad (2)$$

d_{ij} is the vertices between i and j . The pheromone values are updated each iteration by all the m ants that have built a solution in the iteration itself. The pheromone τ_{ij} , which is associated with the edge joining vertices i and j , is updated as follows:

$$\tau_{ij} = (1 - \rho) \cdot \tau_{ij} + \sum_{k=1}^m \Delta\tau_{ij}^k \quad (3)$$

where ρ is the evaporation rate, m is the number of ants and $\Delta\tau_{ij}^k(t)$ is the quantity of pheromone laid on edge (i, j) by ant k :

$$\Delta\tau_{ij}^k = \left\{ \begin{array}{ll} \frac{Q}{L^k} & \text{if ant } k \text{ used edge } (i, j) \text{ in its tour} \\ 0 & \text{otherwise} \end{array} \right\} \quad (4)$$

Q is a constant and L^k is the length of the tour constructed by ant k .

The pseudo code of the ACO procedure is as follows:

Random initialization of the pheromone value

Do

For each iteration

For each ant

Compute of the probability P according to (1)

Determine the P max

End

Compute OF

End

Deduce the best OF

Update pheromone values according to (3)

End

Report the best solution

END

Algorithm1. Pseudo code of ACO

3 Application to the Optimal Design of the Sallen Key Band

Pass Filter:

The architecture that has been used to implement the second order band-pass filter is the Sallen-Key Topology. This topology is chosen due to its simplicity compared to other known architectures such as multiple feedback and state variable. The circuit diagram below shows a second order Sallen-Key band pass filter:

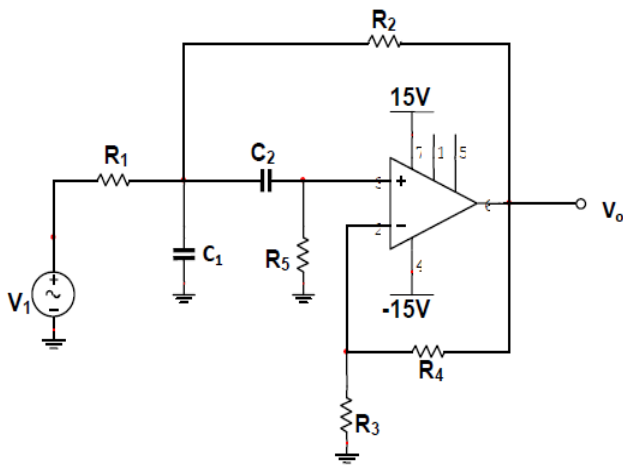


Fig.4: Second Order Sallen-Key Band-pass filter with Gain (A) >1 [1]

Table 1 illustrates the specifications for the desired band-pass filter. By using the following filter parameters, the required filter characteristic is simulated with MATLAB

Table 1: Sallen key band pass Filter specifications:

| | |
|-----------------------|-------|
| Center frequency | 15kHz |
| Stop band attenuation | -20dB |
| Pass band ripple | 0.1dB |
| V _{p-p} | 10mV |

The general transfer function of a second order band pass filter is given as:

$$H(s) = \frac{a_2 s}{s^2 + b_1 s + b_0} \quad (5)$$

The transfer function of the second order Sallen-Key band pass filter in Fig. 4 is:

$$H(s) = \frac{s C_2 R_2 R_3}{s^2 C_1 C_2 R_1 R_2 R_3 + s [C_2 R_2 R_3 (1 - G) + C_2 R_1 R_3 + C_2 R_1 R_2 + C_1 R_2 R_3] + (R_1 + R_2)}$$

The above equation can be simplified by setting $R_1 = R_2 = R$, $R_3 = 2R$, $C_1 = C_2 = C$ this is known as the equal component Sallen-Key band-pass filter

$$H(s) = \frac{sCRG}{s^2 C^2 R^2 + sCR(3-G) + 1} \quad (6)$$

Resonant frequency: $f_0 = 1/2\pi CR$; or $\omega_0 = 1/CR$

Bandwidth: $\beta = f_0/Q$;

Op-amp gain: $G = 1 + R_4/R_3$;

Gain at ω_0 : $A = G/(3-G)$;

Quality factor: $Q = 1/(3-G)$;

The poles of the transfer function are:

$$S_{1,2} = [(G - 3)/RC \pm \sqrt{\{(3 - G)/RC\}^2 + 4(1/RC)^2}] / 2$$

From equation (5) it can be seen that the quality factor is governed by the term G (op-amp gain). Hence, the quality factor (Q) can be varied via the inner gain (G) without modifying the center frequency. A drawback is, however, that Q and A (gain at center frequency) cannot be adjusted independently. When G approaches the value of 3, A and Q tend to infinitely increase and cause the circuit to oscillate. As G grows greater than 3, Q becomes negative and consequently, A becomes negative too, thus from equation (5), the s – coefficient is equal to zero indicating that H(s) has right half-plane poles. This problem can be solved by adding an input buffer that gives a gain adjustment so as to just compensate for a Q adjustment with a change in the input gain. This will increase the number of components used for design and construction thereby raising the cost of the circuit. Substituting, the above transfer function can be written in standard form as:

$$H(s) = \frac{sA(\omega_0/Q)}{s^2 + (\omega_0/Q)s + \omega_0^2} \quad (7)$$

Let the design components be:

$$C = 10nF, R_3 = 10k, R_4 = 10k, f_0 = 15kHz$$

$$R = 1/(2*\pi*15000 * 10 * 10^{-9}) = 1.06k$$

$$G = 1 + (10/10) = 2$$

$$A = 2 / (3 - 2) = 2$$

$$Q = 1 / (3 - 2) = 1$$

$$\text{Bandwidth} = f_o / Q = 15 \text{ kHz} / 1 = 15 \text{ kHz}$$

The transfer function:

$$H(s) = \frac{198520 s}{s^2 + 94260s + 8.88 \text{ E}09}$$

The Quality factor can be varied by varying the gain G through the resistor R₄ or R₃. In this paper, R₃ is chosen to be constant at 10k, while R₄ is chosen as the resistor to be varied. Thus, the different values of Q will be obtained for R₄ = 10k, 16k, 17.5k, 18.75k, 19k, 19.9k from the table below:

Table 2: Values of R₄ and respective Q

| R ₄ (kΩ) | 10 | 16 | 17.5 | 18.75 | 19 | 19.9 |
|---------------------|-----|-----|------|-------|----|------|
| Q | 1.0 | 2.5 | 4 | 8 | 10 | 100 |

By using the transfer function, the frequency response of the filter at varying Q's can be plotted using MATLAB to verify the design.

The cutoff frequency (ω_L , ω_H) and the selectivity factor (Q₁, Q₂) of filter, which depend only on the values of the passives components

For comparison reasons, the specification chosen here is:

$$Q_1=0.7654$$

$$Q_2=1.8478$$

The values of the resistors and capacitors to choose must be able to generate ω_L , ω_H , Q₁ and Q₂ approaching the specified values. For this, define the Total Error (TE) which expresses the offset values, of the cut-off frequency and the selectivity factor, compared to the desired values, by:

$$TE = \alpha \Delta\omega + \beta \Delta Q \tag{8}$$

Where

$$\Delta\omega = \frac{|\omega_L - \omega| + |\omega_H - \omega|}{\omega}$$

$$\Delta Q = |Q_1 - \frac{1}{0.7654}| + |Q_2 - \frac{1}{1.8478}| \tag{9}$$

The objective function considered is the Total Error which is calculated for the different values of α and β . The decision variables are the resistors and capacitors forming the circuit.

4 SIMULATIONS & RESULTS:

In this section ACO algorithm is applied to perform optimization of a second order Sallen-Key band pass filter. The optimal values of resistors and capacitors forming the considered filter and the performance.

Associated with these values for the different series are shown in Table 3 :

Table 3: Values of components and related filter performances

| | Alpha | Beta | C(pf) | R ₄ (K) | F _L (KHz) | F _H (KHz) | B.W. (KHz) | Q | F _o (KHz) |
|-------|---------|---------|--------|--------------------|----------------------|----------------------|------------|--------|----------------------|
| ACO 1 | 0.985 | 0.015 | 393.07 | 18.693 | 14.020 | 15.980 | 1.9598 | 7.6538 | 15.00 |
| ACO 2 | 0.99 | 0.01 | 139.35 | 18.945 | 14.209 | 15.791 | 1.5829 | 9.4762 | 15.00 |
| ACO 3 | 0.981 | 0.009 | 223.92 | 18.995 | 14.246 | 15.754 | 1.5075 | 9.9500 | 15.00 |
| ACO 4 | 0.9999 | 0.0001 | 850.75 | 19.899 | 14.925 | 15.075 | 150.7538 | 99.5 | 15.00 |
| ACO 5 | 0.99985 | 0.00015 | 736.33 | 19.849 | 14.887 | 15.113 | 226.1307 | 66.33 | 15.00 |
| ACO 6 | 0.99993 | 0.00007 | 194.07 | 19.899 | 14.925 | 15.075 | 150.7538 | 99.5 | 15.00 |
| ACO 7 | 0.5 | 0.5 | 631.86 | 10 | 7.5 | 22.5 | 15 | 1 | 15.00 |
| ACO 8 | 0.9 | 0.1 | 796.48 | 15.980 | 11.985 | 18.015 | 6.0302 | 2.4875 | 15.00 |
| ACO 9 | 0.8 | 0.2 | 980.10 | 13.317 | 9.9874 | 20.013 | 10.025 | 1.4962 | 15.00 |

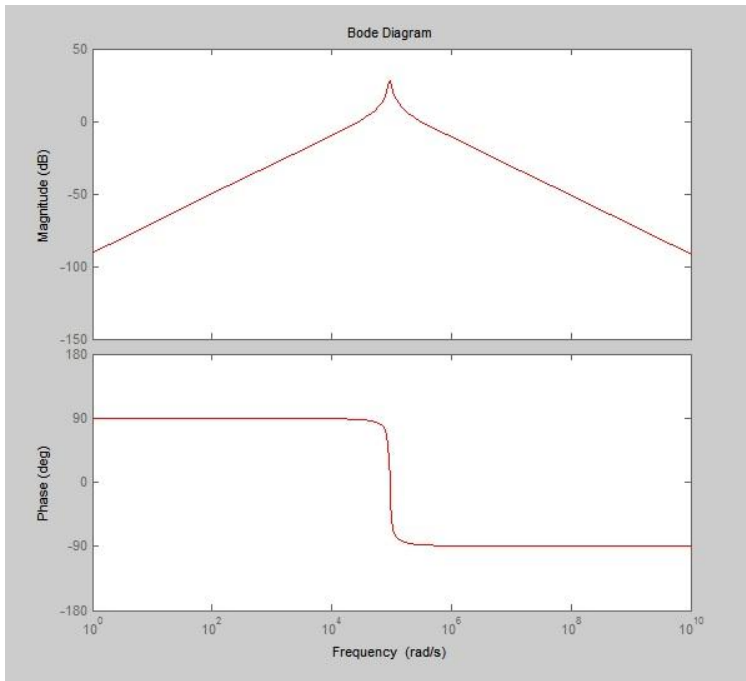


Fig. 5: Simulation of ACO1.

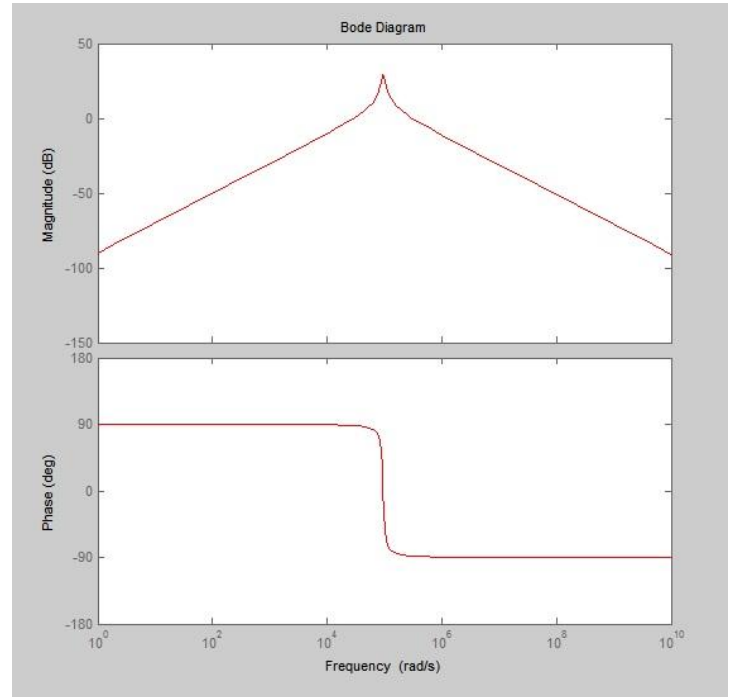


Fig. 7: Simulation of ACO3.

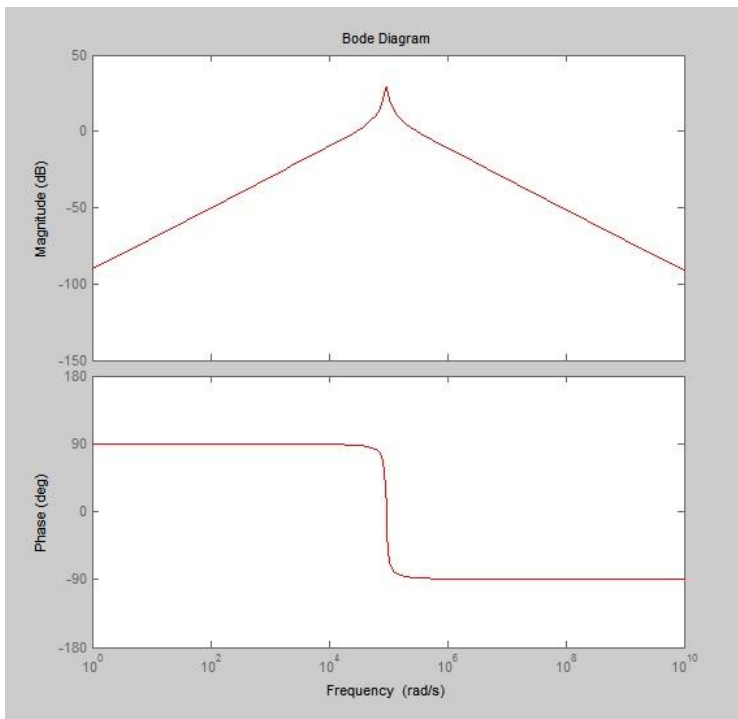


Fig. 6: Simulation of ACO2.

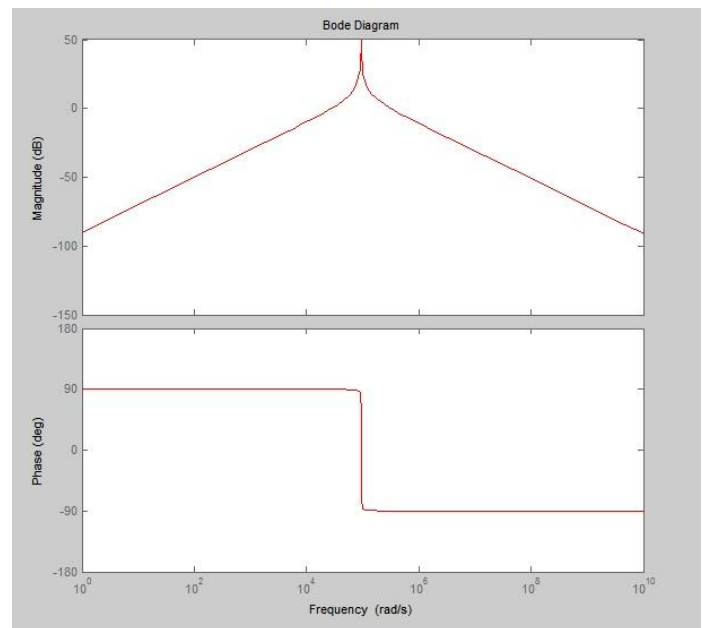


Fig. 8: Simulation of ACO4.

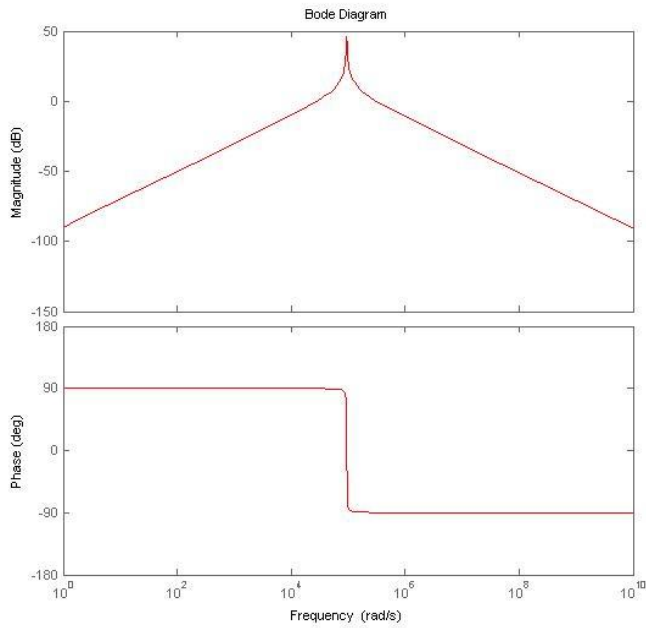


Fig. 9: Simulation of ACO5

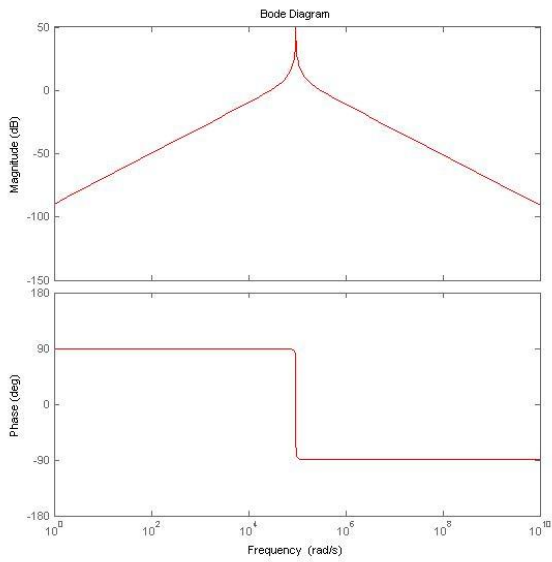


Fig. 10: Simulation of ACO6.

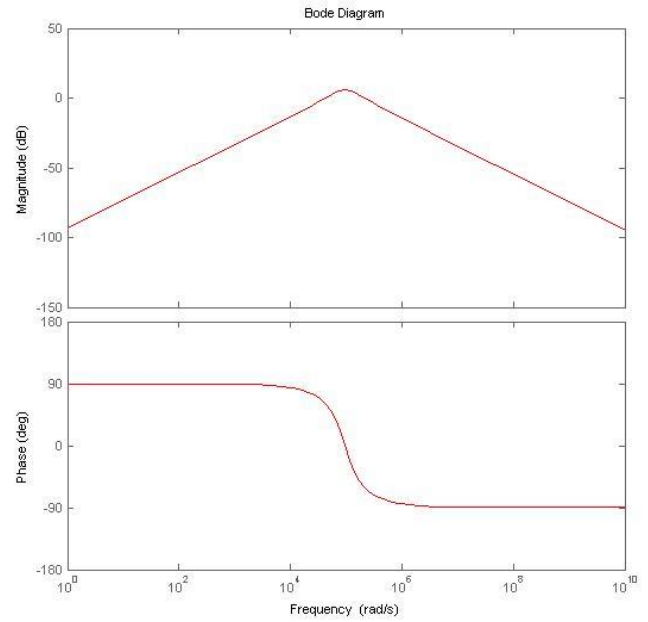


Fig. 11: Simulation of ACO7

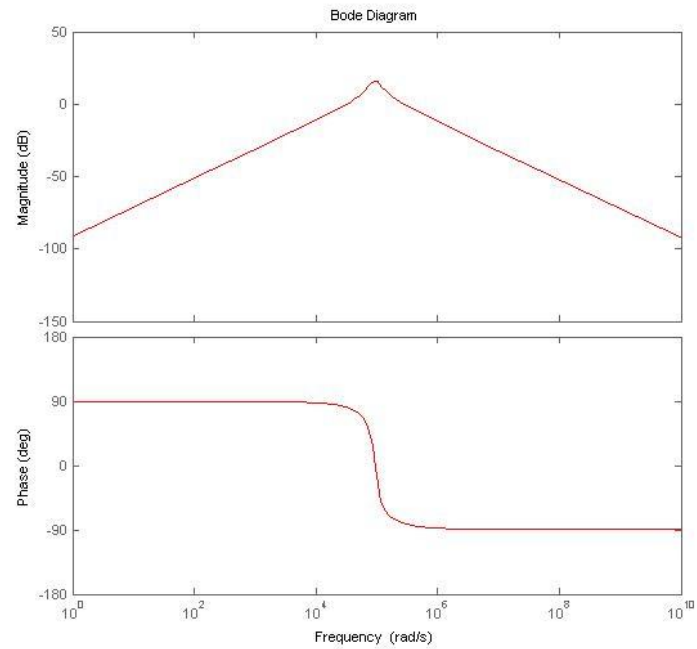


Fig. 12: Simulation of ACO8

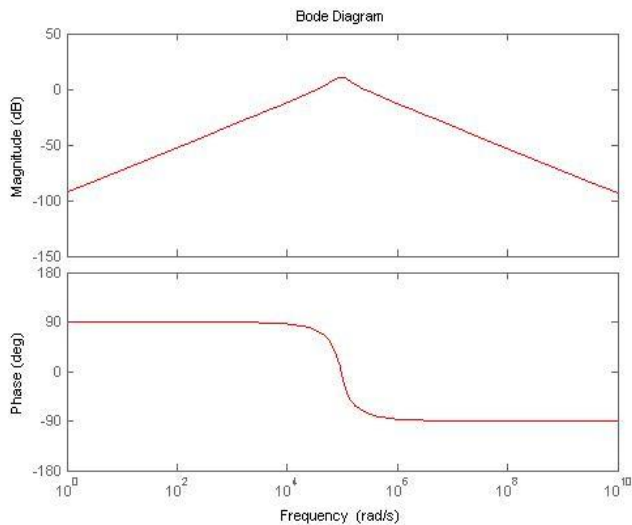


Fig. 13: Simulation of ACO9

5 CONCLUSION:

In this work an application of the Ant Colony Optimization is presented for optimal design of a Second Order Sallen Key Analog Band pass filter. Investigation for the selection of passive components has been done. The design of the analog filter with high accuracy and short execution time is successfully realized using the ACO. It is shown that the tolerances of the spacing values associated to the components affect significantly the performance of the filter. MATLAB simulations confirm the validity of the proposed algorithms.

For the future work one can apply the proposed ACO technique in dealing with the optimal design of complex analog circuits.

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