

# FINITE ELEMENT ANALYSIS OF FLIGHT CONTROL SERVO ACTUATOR TEST LOADING RIG

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**Abstract** – The outline of this paper is to present the finite element analysis of flight control servo actuator test loading rig, also proposes to maintain the life cycle of the assembly is greater than 20 Million Cycles and also maintain the minimum structural stiffness of **200x10<sup>5</sup> N/mm**. The objective of this work is to carry out Dynamic analysis of loading rig and validate the results. The software used for the modelling is SOLID WORKS 2012 and the ANSYS software is used for the analysis of loading rig. The result obtained from the ansys and theoretical calculations are valid.

**Key Words:** Ansys, Solid Works, etc...

## 1. INTRODUCTION

Servo Actuator loading rig is an important rig for simulating aerodynamic load and inertia of flight control actuators on ground. The rig will be used for carrying out different tests like Endurance Cycling, loaded frequency response, loaded rate, static and dynamic stiffness on flight control actuators.

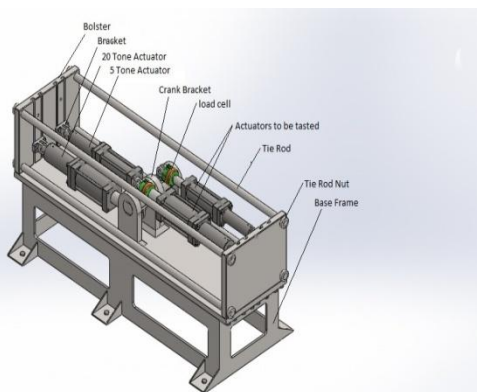


Fig. 1.1 Flight control Actuator Test Loading Rig.

There shall be two independent loading actuators of 5 tonne and 20 tonne capacities, two parallel sliding

channels to independently cater to test actuators requiring different stall loads. The hydraulic power pack shall fulfill the load and actuator rate requirement.

In the test loading rig the servo actuators are placed at the bottom sides and the actuators to be tested i.e. flight control actuators are placed at the upper side. The servo actuators and flight control actuators are connected each other with the help of crank and bracket assembly. The required pressure is applied to the servo actuators with the help of power pack and the same opposite pressure is applied to the flight control actuators with the help of another power pack. The type of load acting on the rig is completely reversible. The operating frequency of the test loading rig is 25Hz. The analysis and calculations are to be carried out for this operating frequency.

## 2. COMPONENTS OF TEST LOADING RIG

### 2.1 Bolster

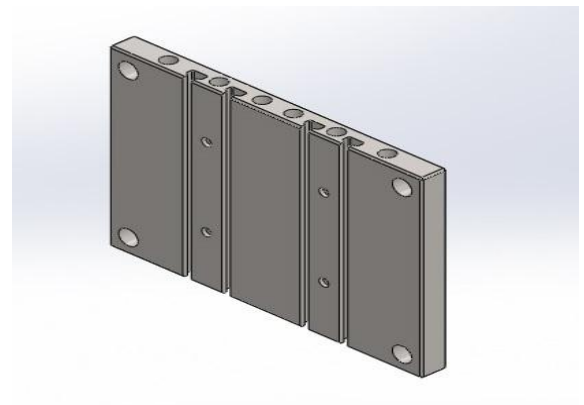


Fig. 2.1 Bolster

Bolsters are the plates which are bolted to the base frame at the both ends of the side plate. Both the bolsters are connected by the four tie rod at their corners. The T slots are made in the bolster to lock the brackets to which actuators are connected. The dynamic load is acting on these bolsters. Because of the dynamic load the suitable design modification and dynamic analysis is to be carried out.

Table 2.1 Details of Bolster

SL. NO.	NAME	MATERIAL	SIZE	WEIGHT	QTY
1.	Bolster	Structural Steel	800mm x 600mm x 65mm	215.3 Kg	02 Nos.

### 2.2 Base Frame

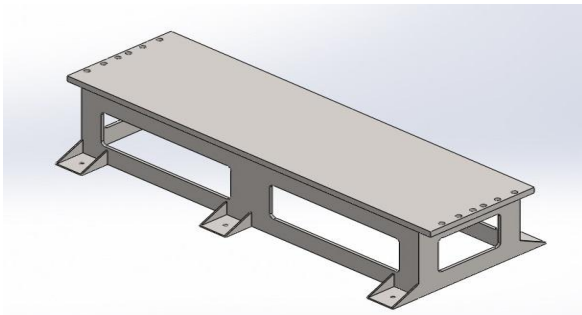


Fig. 2.2 Base Frame

Most of the test rigs are mounted on Base frames. Actuators, Bolsters, crank brackets are mounted on the base frame to carry its weight, to maintain its alignment and to assist in carrying the dynamic loads which every actuator generates. Test rig base frame needs an effective design technology to ensure that the base frame as designed performs the required functions, and maintains its integrity. There is also a need to maximize the life of the test rig base frame under the loads to which it is exposed.

### 2.3 Bracket

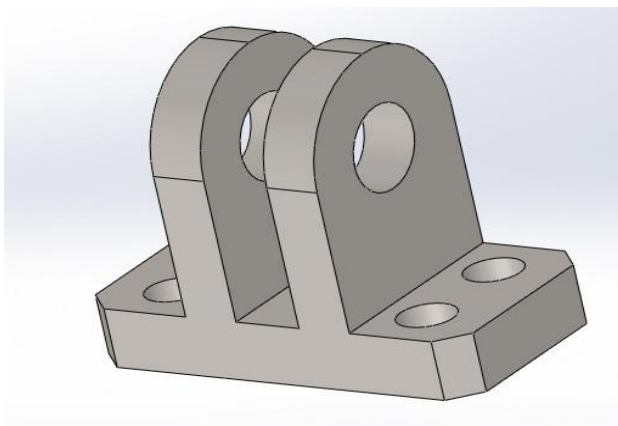


Fig. 2.3 Bracket

The test loading rig has the eight numbers of brackets. The bracket pins are placed in the each bracket. The both the ends of the actuators are connected to the bracket. Bolsters are connected to the crank with the help of M20 cap screws and connected to the bolster with the help of M20 bolts.

### 2.4 Rig Tie Rod

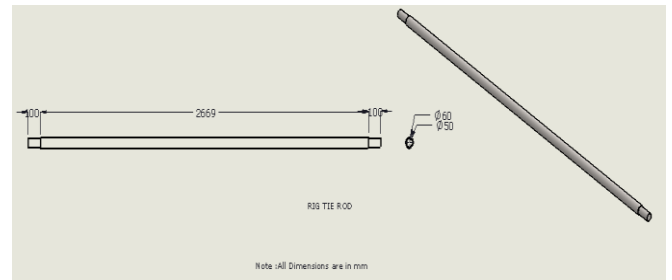


Fig. 2.4 Rig Tie Rod

In this test loading rig the four tie rods are used. Bolsters are connected at both the ends of tie rod.

Table 2.2 Details of Rig Tie Rod

SL. NO.	NAME	MATERIAL	SIZE	WEIGHT	QTY
1.	Rig Tie Rod	EN 8	Ø60m m × length 2869m m	61.9 Kg	04 Nos.

## 3. DESIGN CALCULATION

### 3.1 Actuator's Longitudinal Stiffness And Damping Factor

Here we are going to use two single acting cylinders. One is the capacity of 5 tonnes and another is the capacity of 20 tonnes.

#### i. 20 Tonne Actuator

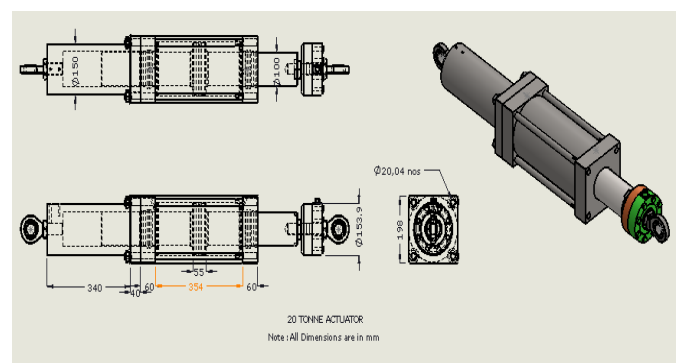


Fig. 3.1 20 Tonne Actuator

Given data:-

Let Outer diameter of Piston (D) = 160 mm

Inner diameter of Piston (d) = 100 mm

Length of Cylinder (L) = 290 mm

Longitudinal Stiffness (K) of cylinder is given by

$$K = \frac{4\beta A^2}{V} \quad (1)$$

Where  $\beta$  = Bulk Modulus of oil =107.45 Bar

A = Area of piston= 12252.2 mm

V = Volume of Cylinder = 3553138 mm<sup>3</sup>

$$K = 181587 \text{ N/mm} \quad (2)$$

Longitudinal Damping (C) of cylinder is given by

$$C = \frac{\pi \rho \theta D l}{\delta} \quad (3)$$

The hydraulic oil of grade Servo 68 is used in the actuators.

Where  $\rho$  = Density of Oil = 890 kg/m<sup>3</sup>

$\nu$  = Kinematic viscosity of oil = 3.25x10<sup>-4</sup> m<sup>2</sup>/s

D = Diameter of Cylinder = 160 mm

$\delta$  =Difference between piston & cylinder=0.025 mm

l = Length of piston = 60 mm

$$C = \frac{\pi \times 890 \times 3.25 \times 10^{-4} \times 0.16 \times 0.06}{2.5 \times 10^{-5}} \quad C = 349 \text{ N-S/mm} \quad (4)$$

ii. 5 Tonne Actuator

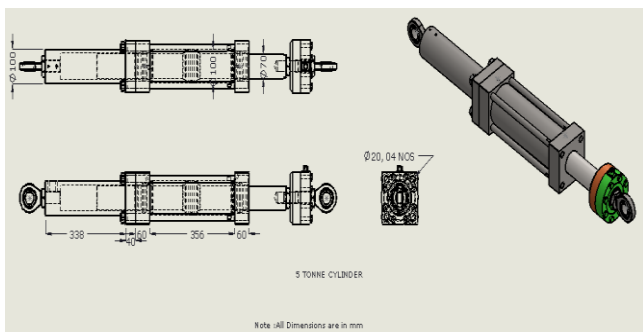


Fig. 3.2 5 Tonne Actuator

Given data:-

Let Outer diameter of Piston (D) = 100 mm

Inner diameter of Piston (d) = 70 mm

Length of Cylinder (L) = 290 mm

Longitudinal Stiffness (K) of cylinder is given by

$$K = \frac{4\beta A^2}{V}$$

Where  $\beta$  = Bulk Modulus of oil =107.45 Bar

A = Area of piston= 4005.5 mm

V = Volume of Cylinder = 161603.88 mm<sup>3</sup>

$$K = 59611 \text{ N/mm}$$

Longitudinal Damping (C) of cylinder is given by

$$C = \frac{\pi \rho \theta D l}{\delta}$$

The hydraulic oil of grade Servo 68 is used in the actuators.

Where  $\rho$  = Density of Oil = 890 kg/m<sup>3</sup>

$\nu$  = Kinematic viscosity of oil = 3.25x10<sup>-4</sup> m<sup>2</sup>/s

D = Diameter of Cylinder = 160 mm

$\delta$  =Difference between piston & cylinder= 0.025 mm

l = Length of piston = 60 mm

$$C = \frac{\pi \times 890 \times 3.25 \times 10^{-4} \times 0.16 \times 0.06}{2.5 \times 10^{-5}} \quad C = 218 \text{ N-S/mm}$$

3.2 Life Cycle

i. Structural Steel

Design endurance limit is given by

$$\sigma_{se} = K_{sr} K_{sz} K_{ld} K_R K_T \sigma'_{se} \quad (8)$$

Where  $K_{sr}$  = surface factor=1

$K_{sz}$  = size factor=0.8

$K_{ld}$  = load factor=1

$K_R$  = reliability factor=0.897 for 90% of reliability

$K_T$  = temperature factor=1 for  $T \leq 450^\circ\text{C}$

$\sigma'_{se}$  = endurance limit of the test specimen=200MPa

$$\sigma_{se} = 1 \times 0.8 \times 1 \times 0.897 \times 1 \times 200 \quad \sigma_{se} = 143.52143.52 \text{ N/mm}^2$$

Results obtained:-

a) Since the endurance limit of the entire component i.e. 132.46 N/mm<sup>2</sup> is very less than the endurance limit of structural steel i.e. 200 N/mm<sup>2</sup>. Hence the lives of all the components are infinite.

ii. EN8

Design endurance limit is given by

$$\sigma_{se} = K_{sr} K_{sz} K_{ld} K_R K_T \sigma'_s$$

Where  $K_{sr}$  = surface factor = 1

$K_{sz}$  = size factor = 0.8

$K_{ld}$  = load factor = 1

$K_R$  = reliability factor = 0.897 for 90% of reliability

$K_T$  = temperature factor = 1 for  $T \leq 450^\circ\text{C}$

$\sigma'_s$  = endurance limit of the test specimen = 270 MPa

$$\sigma_{se} = 1 \times 0.8 \times 1 \times 0.897 \times 1 \times 200 \quad \sigma_{se}$$

$$\sigma_{se} = 143.52193.77 \text{ N/mm}^2$$

Results obtained:-

a) Since the endurance limit of the rig tie rod i.e. 193.77 N/mm<sup>2</sup> is less than the endurance limit of EN8 i.e. 270 N/mm<sup>2</sup>. Hence the life of the rig tie rod is infinite.

#### 4. ANALYSIS BY ANSYS

The ANSYS program is used to carry out the Static, Modal and harmonic response of the test loading rig. For our project we have used ANSYS WORK BENCH 14 for FEA analysis of the machine elements.

##### 4.1 Modal Analysis

A system with N degrees of freedom has N natural frequencies of free vibration and N mode shapes of free vibration, one associated with each natural frequency. The following figure shows the mode shapes of the test loading rig.

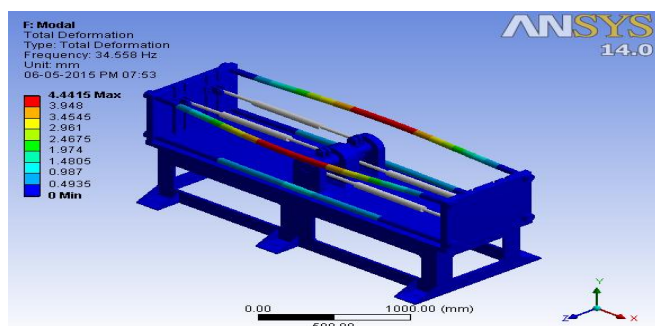


Fig.4.1 First mode Shape

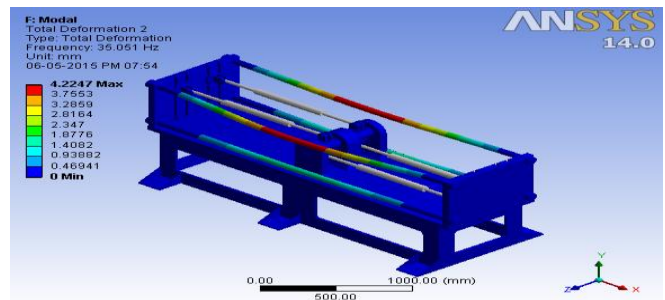


Fig.4.2 Second mode Shape

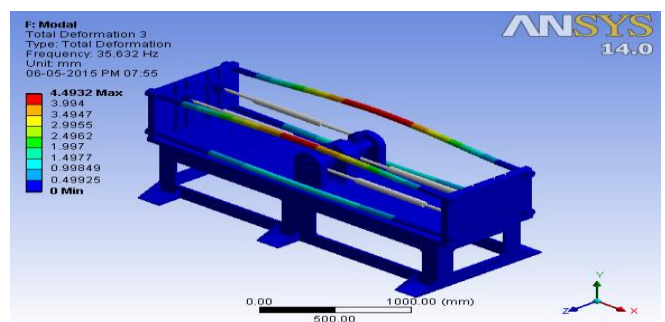


Fig.4.3 Third mode Shape

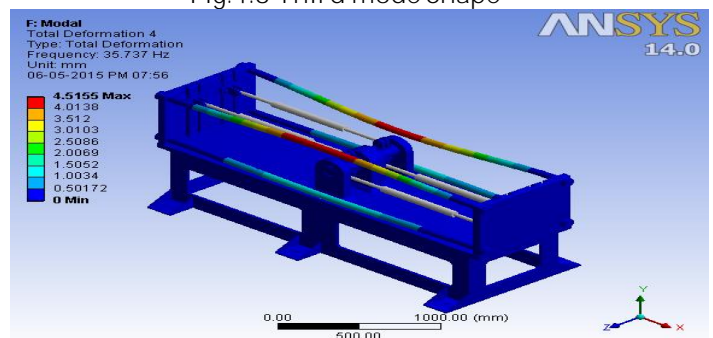


Fig.4.4 Fourth mode Shape

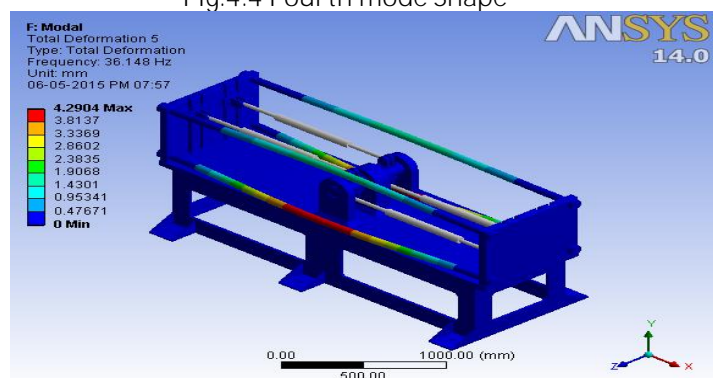


Fig.4.5 Fifth mode Shape



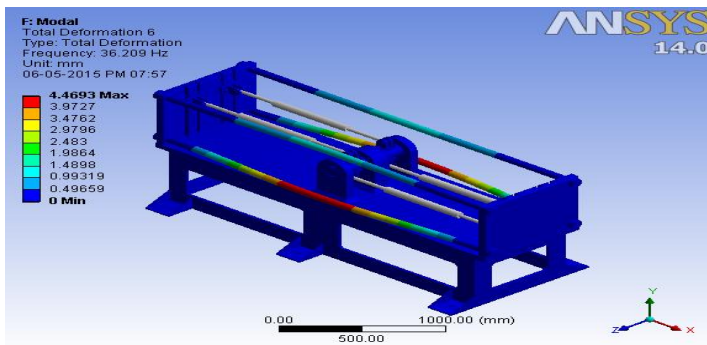


Fig.4.6 Sixth mode Shape

Table 4.1 Details of mode shape

MODAL ANALYSIS		
MODE NO.	DEFORMATION (mm)	FREQUENCY (Hz)
1.	4.4415	34.558
2.	4.2247	35.051
3.	4.4932	35.632
4.	4.5155	35.737
5.	4.2904	36.148
6.	4.4693	36.209

Results obtained:-

a) The first mode of the modal analysis has the natural frequency of 34.558 Hz and it goes on increases as the number of mode shapes increases. The natural frequency of first mode shape i.e. 34.558 Hz is higher than the working frequency of the system i.e. 25Hz. Hence the design is safe.

#### 4.7 Harmonic Response Analysis Of Test Loading Rig

Harmonic response is continuous periodic response in the whole system caused by mechanical load. Here, the ANSYS method is used for harmonic response analysis, namely, the responses in the structure are determined in different frequencies, responses are found in corresponding frequency curve, peak values in the curves are observed.

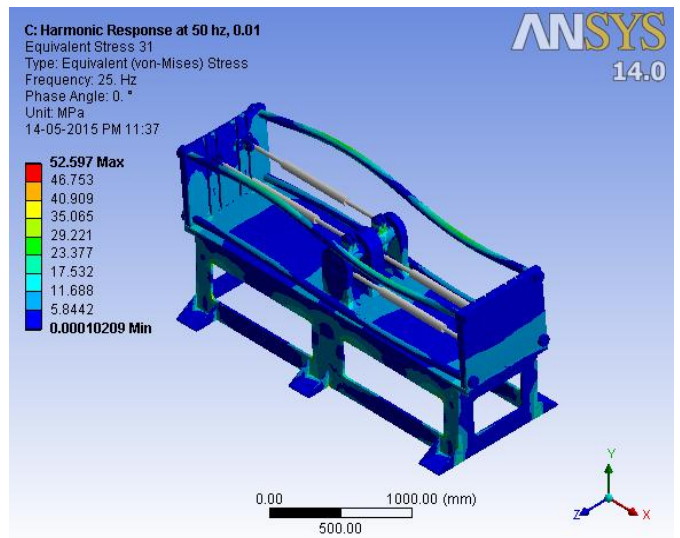


Fig 4.12 Von-mises stress in Test loading Rig at 25Hz

Results obtained:-

a) Maximum Stress in the Test Loading Rig = 52.597N/mm<sup>2</sup>

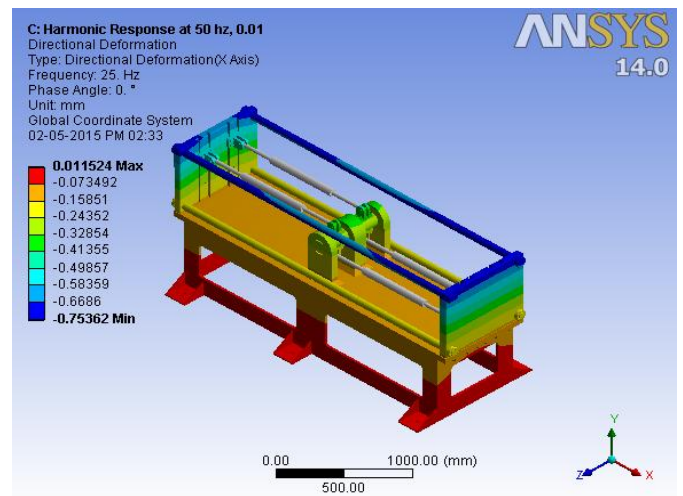


Fig 9.13 Directional Deformation of Test Loading Rig at 25Hz

Results obtained:-

a) Maximum Deformation in the Test Loading Rig =0.011524mm

#### 4.8 Structural Stiffness

Total load acting on the system P=25 tonne

Maximum deflection of the system  $\delta = 0.011524\text{mm}$

$$\text{Structural stiffness} = \frac{P}{\delta} = \frac{25 \times 9.81 \times 1000}{0.011524} = 245.28 \times 10^5 \text{ N/mm}$$

i. Phase Diagram For Applied Forces

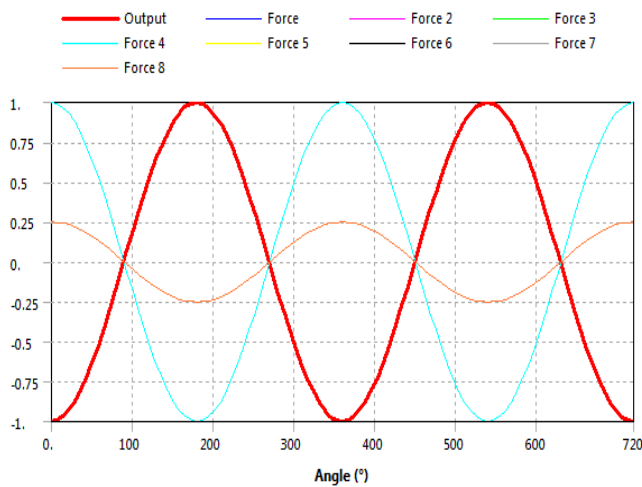


Fig 9.14 Phase diagram of for applied forces

The Fig. 9.14 shows the phase diagram of test loading rig for applied forces. Phase Response plots show a response over a range of phase angles, so you can determine how much a response lags behind the applied load. There are two types of forces are acting on the loading rig i.e. 20 tonne and 5 tonne. Both the forces are acting in a sine wave manner. However, unlike Frequency Response plots that shows response amplitude over a frequency range.

5. RESULTS AND DISCUSSION

The following results have been obtained by ANSYS and theoretical calculations for different parts and the results are compared.

Table 5.1 Stress and deflection results

Component	ANSYS results	Theoretical results				
	Maximum stress in N/mm <sup>2</sup>	Mean stress in N/mm <sup>2</sup>	Alternating Stress N/mm <sup>2</sup>	Modified Good Man's Equation Value	Endurance Limit N/mm <sup>2</sup>	Life cycles
Rig Tie Rod	26.088	38.30	12.948	0.1134	193.77	Infinite
Bolster	29.661	114	14.816	0.0967	143.52	Infinite
Crank Bracket	29.411	19.62	14.64	0.0957	143.52	Infinite
Bracket	16.458	75	8.2205	0.0536	143.52	Infinite
Bracket Pin	0.006	2.35	14.816	0.0967	143.52	Infinite

Since all the stresses induced are well below the yielding stress of the material. The material is safe.

The table below shows the buckling results for rig tie rod.

Table 5.2 Buckling results

Component	Critical buckling load in Tonne	Load acting on the component in Tonne
Rig Tie rods in compression	62.20	12.5

Since the actual loads acting on the tie rod is very less than the critical loads, hence this component will not buckle.

6. CONCLUSION

- i. Life cycle of the test loading rig infinite i.e. greater than 20 Million Cycles.
- ii. The structural stiffness of test loading rig is  $245.28 \times 10^5$  N/mm i.e. Greater than  $200 \times 10^5$  N/mm.
- iii. The stresses induced in all the components of test loading rig within the value of working stress i.e. 125 N/mm<sup>2</sup>. Hence the component does not undergo yielding.
- iv. Directional deformation of test loading rig i.e. 0.011524mm, less than 0.05mm.
- v. The buckling analysis is done for the tie rods in compression. The critical load in tie rod is much less than the actual load acting on this component, hence buckling will not occur.

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## BIOGRAPHIES



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