

# IoT Based Electric Vehicle Charging System

Ms. Rutuja Rajole<sup>1</sup>, Mrs. Geetanjali Khot<sup>2</sup>, Mr. Gajanan Udas<sup>3</sup>

<sup>1</sup>Design Engineer, Tata Technologies Pune.

<sup>2</sup>Deputy General Manager, Tata Motors, Pune

<sup>3</sup>Senior Team Lead, Tata Technologies, Pune

\*\*\*

## Abstract -

Electric vehicles are a new and forthcoming technology in the transportation and power sector that have numerous benefits in terms of profitable and environmental. This study presents a comprehensive review and evaluation of different types of electric vehicles and its associated outfit in particular battery bowl and charging station. A comparison is made on the marketable and prototype electric vehicles in terms of electric range, battery size, bowl power and charging time. The different types of charging stations and norms used for charging electric vehicles have been outlined and the impact of electric vehicle charging on mileage distribution systems is banded. The methodology presented then was time- and cost-effective, as well as scalable to other associations that enjoy charging stations. Electric vehicles (EVs) are getting decreasingly popular in numerous countries of the world. EVs are proving further energy effective and environmental friendly. However, the lack of charging stations restricts the wide relinquishment of EVs in the world. As EV operation grows, further public spaces are installing EV charging stations.

**Key Words:** ATMEGA8, RFID, Proximity Sensor, ESP8266, Touch Screen.

## 1. INTRODUCTION

### 1.1 Necessity

Since the early 2000, India's crude oil painting significances have risen exponentially. The demand for oil painting grew by 5.1 in 2016, advanced than the world's largest net importers, the US(0.7) and China(2.9), making India the world's third largest crude oil painting consumer. India ranks as the third largest carbon emitting country in the world counting for 6 of the global carbon dioxide emigrations from energy combustion. According to the WHO Global Air Pollution Database (2018), 14 out of the 20 most weakened metropolises of the world are in India<sup>4</sup>. Rising population – a sustainable mobility challenge India's current population of 1.2 billion is anticipated to reach 1.5 billion by 2030. India is the world's fourth largest patron of internal combustion machine (ICE) grounded motorcars. The growth in the automotive request in India has been the loftiest in the world,

growing at a rate of 9.5 in 2017. An adding uptake in electric vehicles is likely to pose a challenge to the being automotive request if the country does not plan its transition towards newer mobility results and develop the needed manufacturing capabilities. Electric Mobility an implicit result for India.

### 1.2 Need

In 2017, Indian government pushed a major policy of dealing at least 6- 7 million EV's in India by 2020. They are planning to vend only EV's by 2030. However, numerous experts in machine assiduity blamed this plan and said that it might be fail. Only reason they have stated, is lack of structure, and majorly lack of 'Charging stations'. Indian government is really trying to push electric vehicle in our ecosystem. However, people are reticent to buy an electric vehicle. Reason people are not buying electric vehicle is 'Range Anxiety'. Range anxiety is solicitude on the part of a person driving an electric vehicle that the battery will run out of power before the destination or a suitable charging point is reached. So what is the point in buying EV? Why would I, you will buy an electric vehicle? Then, charging station plays vital part.

### 1.3 Motivation

Electric vehicles are a new and forthcoming technology in the transportation and power sector that have numerous benefits in terms of profitable and environmental. Electric vehicles (EVs) are getting increasingly popular in numerous countries of the world. EVs are proving further energy effective and environmental friendly. However, the lack of charging stations restricts the wide relinquishment of EVs in the world. This has motivated design each along so that it is stoner friendly system.

### 1.4 Objective

- i. To design IoT based electric vehicle charging system.
- ii. To design user friendly and reliable system.
- iii. To provide fast charging to electric vehicle.

## 2. Analysis & Design Approach

### 2.1 Block Diagram:

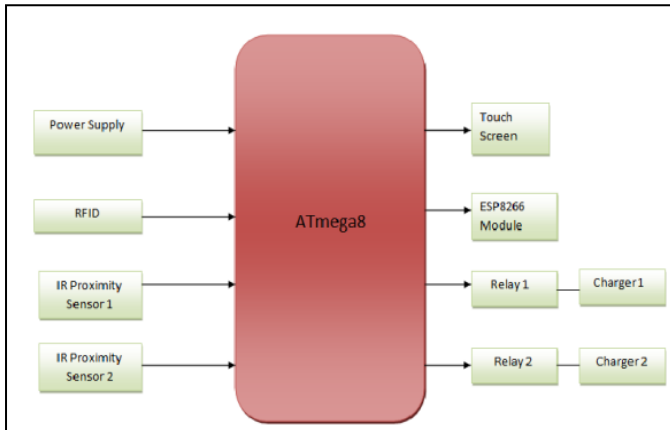


Fig 1 Block Diagram of the system

### 2.2 Block Diagram Description:

- Here we used ATmega8 controller for this project.
- Power Supply, which is the first block, decided to be the dual power supply of 12v, 5v. The 5v supply is for controller and the 12v is required for the relays.
- The RFID is used for the identification of the users. We will provide RFID card to the users.
- The IR Proximity Sensors are used to check the availability of charging slots. If the place is available, then message will be displayed on touch screen display.
- The Esp8266 module is used to send messages to the user and for collecting data and analyzing the data.
- The various messages are displayed to the user about charging status, amount, and time on Touch screen.

### 2.3 Flow Chart

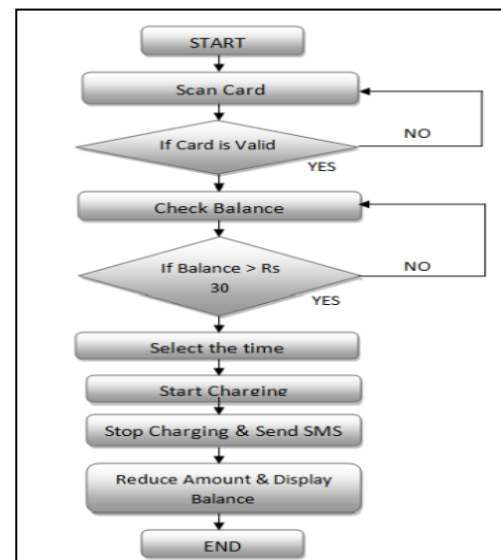


Fig 2 Flow Chart

### 2.4 Component Used

#### 2.4.1 ATMEGA8

It's an 8-bit CMOS technology grounded microcontroller belonging to the AVR family of microcontrollers developed in 1996. It is erected on RISC (Reduced Instruction Set Computer) armature. ATmega8 microcontroller consists of 1KB of SRAM, 8KB of flash memory, 512 bytes of EEPROM, 23 general purpose I/ O lines, 32 general-purpose working registers, three flexible timekeeper/ Counters, internal and external interrupts, a periodical programmable USART. The device operates between 2.7-5.5 volts. By executing important instructions in a single timepiece cycle, the device achieves throughputs approaching one MIPS per MHz, balancing power consumption and processing speed.

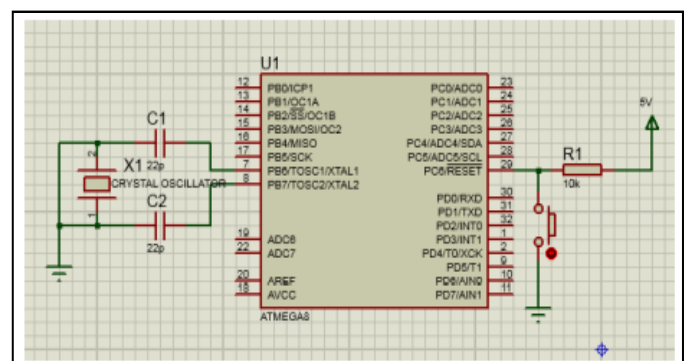


Fig 3 Block diagram of ATMEGA8

### 2.4.2 Power Supply

Power Supply Units (PSU) do not supply systems with power- rather they convert it. Specifically, a power force converts the interspersing high voltage current (AC) into direct current (DC), and they regulate the DC affair voltage to the fine forbearance needed for ultramodern computing factors. Then we used binary power force of 12V and 5V, in which 12V goes to relay and 5V is for regulator.

### 2.4.3 RFID

Radio Frequency Identification is a type of communication between a transmitter (transponder or tag) and a receiver (reader). The system works fully automatically and is used for contactless communication, identification and localization of objects such as goods, medicines, vehicles or living beings.

#### EM-18 Features and Specifications

- Operating voltage of EM-18: +4.5V to +5.5V
- Current consumption:50mA
- Can operate on LOW power
- Operating temperature: 0°C to +80°C
- Operating frequency:125KHz
- Communication parameter:9600bps
- Reading distance: 10cm, depending on TAG
- Integrated Antenna



Fig 4 RFID Module

### 2.4.4 IR Proximity Sensor

Proximity Sensors are used to detect objects and obstacles in front of the sensor. Sensor keeps transmitting infrared light and when any object comes near, the sensor detects it by monitoring the reflected light from the object.

#### Features of IR Proximity Sensor:

- IR transmitter
- Ambient light protected IR receiver
- 3 pin easy interface connectors
- Indicator LED & Power LED

- Distance 2cm to 30cm
- Can differentiate between dark and light colors.
- Active Low on object detection
- 3.3 to 5V operation



Fig 5 IR Proximity Sensor

### 2.4.5 ESP8266

The ESP8266 Wi-Fi Module is a self-contained SOC with integrated TCP/IP protocol stack that can give any microcontroller access to your Wi-Fi network. The ESP8266 is capable of either hosting an application or offloading all Wi-Fi networking functions from another application processor.

#### Features of ESP8266:

- 802.11 b/g/n • Wi-Fi Direct (P2P), soft-AP
- Integrated TCP/IP protocol stack
- Integrated TR switch, balun, LNA, power amplifier and matching network
- Integrated PLLs, regulators, DCXO and power management units
- +19.5dBm output power in 802.11b mode
- Power down leakage current of < 2ms
- Standby power consumption of < 1.0mW (DTIM3)
- 4MB Flash Memory
- Integrated low power 32-bit CPU could be used as application processor
- SDIO 1.1 / 2.0, SPI, UART • STBC, 1×1 MIMO, 2×1 MIMO
- A-MPDU & A-MSDU aggregation & 0.4ms guard interval
- Wake up and transmit packets in < 2ms
- Standby power consumption of < 1.0mW (DTIM3)

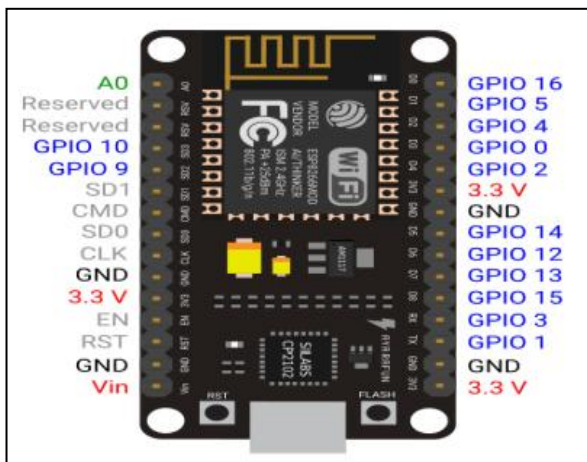


Fig 6 ESP8266 Module

### 2.4.6 Relays

Relays are electric switches that use electromagnetism to convert small electrical stimuli into larger currents. These conversions occur when electrical inputs activate electromagnets to either form or break existing circuits. Features of Relay:

- Max Current: 5A AC/DC (max).
- Max Voltage: 250V AC/30V DC.
- Nominal Voltage: 12V.
- Coil resistance: 270Ω.
- Coil Current: 44.4mA.
- Operating Voltage: 8.6 to 21.6V.

### 2.4.7 Touch Screen

The touch screen enables the user to interact directly with what is displayed, rather than using a mouse, touchpad, or other such devices (other than a stylus, which is optional for most modern touch screens).

Features of Touch Screen:

- 320 x 240 Resolution
- RGB 65K true to life colors
- TFT screen with integrated resistive touch panel
- 4 pin TTL serial interface
- 4M Flash memory for User Application Code and Data
- On board micro-SD card slot for firmware upgradation
- Visual Area: 57.6mm(L)×43.2mm(W)
- Adjustable Brightness: 0~180 nit, the interval of adjustment is 1%
- 5V65mA power consumption
- Compatible with Raspberry Pi A+, B+, Pi 2, Pi 3, Arduino.

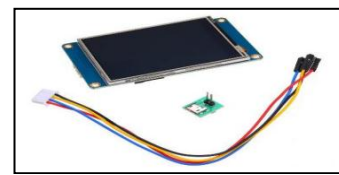


Fig 7 Touch Screen

## 3. Hardware Design

### 3.1 Circuit Design

#### 3.1.1 Power Supply

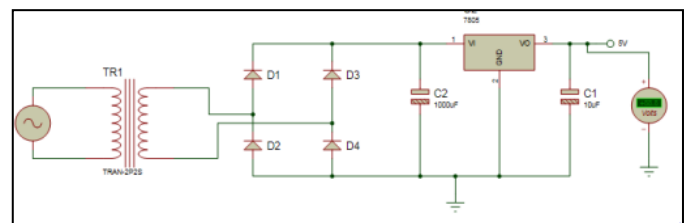


Fig 8 Power Supply Simulation

#### 3.1.2 Main Circuit Diagram

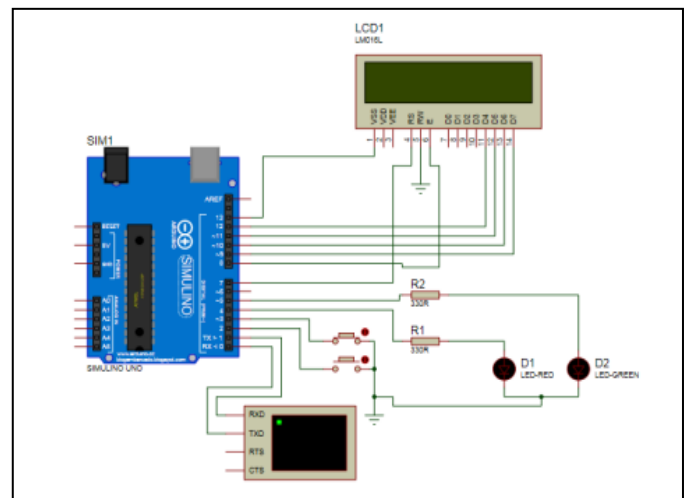


Fig 9 Circuit Diagram of system

### 3.2 Calculation

#### Power supply Calculations:

- **Voltage Rating:**

As we require  $V_{ldc}$  of almost 8V so by considering the voltage drop across diodes and other components. We decided to use 12V transformer.

$$As, V_{rms} = V_m / \sqrt{2}$$

$$\therefore V_m = V_{rms} * \sqrt{2}$$

$$\therefore V_m = 16.97V$$

$$As, V_{ldc} = 2 V_m / \pi$$

$$\therefore V_{ldc} = 10.80V$$

By considering the diode drop of around 1.4 V we get,

$$\therefore V_{ldc} = 9.54V$$

This is more than sufficient for IC 7805 for generating output of +5V.

- Current Rating As we require  $I_{ldc}$  of almost 1A so we decided to use 1A transformer current rating. If we choose 1A then we get 0.9A as  $I_{ldc}$  which is not sufficient.

$$As, I_{rms} = I_m / \sqrt{2}$$

$$\therefore I_m = I_{rms} * \sqrt{2}$$

$$\therefore I_m = 2.82A$$

$$As, I_{ldc} = 2 I_m / \pi$$

$$\therefore I_{ldc} = 1.79A$$

- Capacitor Calculations:

If we assume that our step down transformer reduces the amplitude of 50 Hz sine wave from 230V to 12V.

The discharge time of the capacitor in this case is  $T_{discharge} = 1 / (2 * f)$

$$As, f = 50Hz$$

$$\therefore T_{discharge} = 10 \text{ ms}$$

Now, at the beginning of each discharge period our capacitor is charged up to the peak value i.e.  $V_{max} = 16.97V$ .

In order to prevent our capacitor voltage going below  $V_{min} = 7V$  in the end of the discharge period, so the capacitor value should be chosen with the equation:

$$C = (I_{max} * T_{discharge}) / (V_{max} - V_{min})$$

$$\therefore C = (1 A * 10 \text{ ms}) / (16.97 - 7)$$

$$C = 1mF$$

## 4. Implementation, Test & Performance

### 4.1 Flow Chart

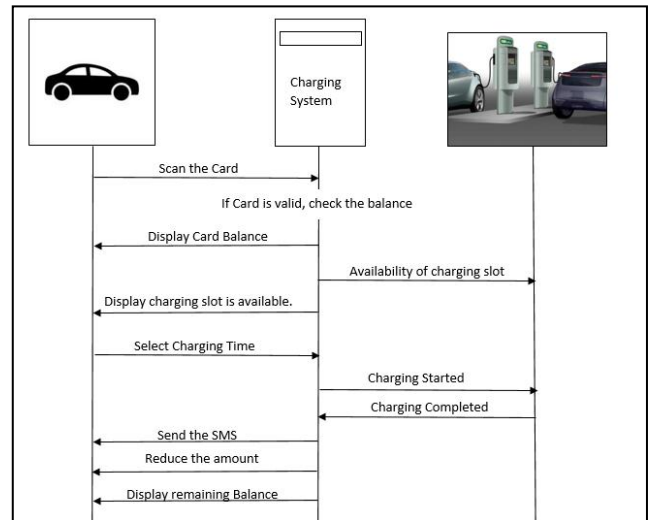


Fig 10 Flow Diagram

Flowchart description:

1. Firstly, customer arrives at the charging station to charge the car.
2. Then he will wait for swiping the card, after swiping the card, the system will check the space for the arrived person.
3. Also, check for availability of either one or two spaces.
4. If space is vacant, the message is shown on the screen that space is vacant; you can charge your vehicle.
5. Then the customer will proceed for the next process.
6. He will swipe the card.
7. After swiping, a balance checking process will be going on in the system.
8. If there is balance in the card, then the system will allow that person, but if there is no sufficient balance, the system will give the message for repeating the process until the available balance is sufficient and display the message to recharge your card.



- After the balance is checked, the customer has to select the timing for charging his vehicle.

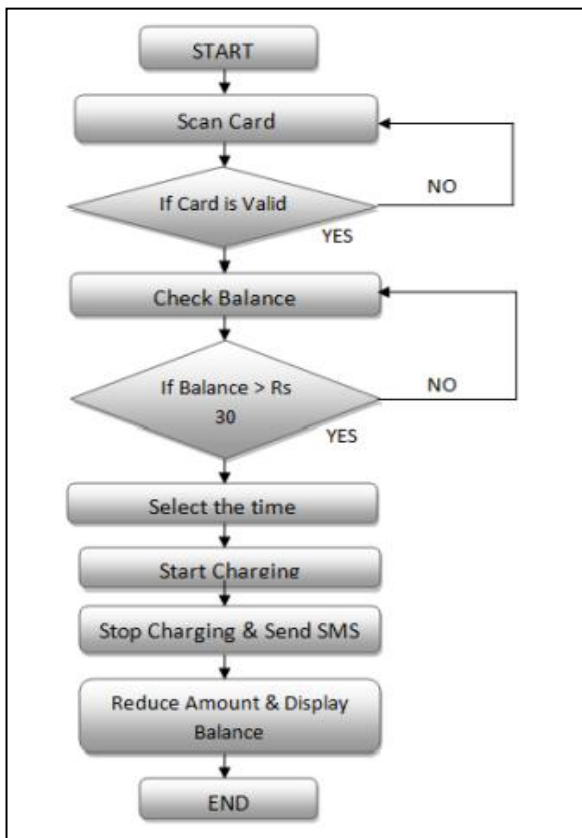


Fig 11 Flow Chart

- Charging will start.
- After charging is finished, the system will display that message that you are charging is done.
- Then the amount is reduced from the customer's account. In addition, final balance will be displayed on screen.

## 5. CONCLUSIONS

The purpose of this project is to provide fast charging to electric vehicle. In the proposed EV charging System, introduction of mobile application will facilitate connectivity user's interaction. The Simulation tool helps on this charging process to simulate behavior an operating condition under different assumptions. The application of IoT approaches has a great potential, once we are able to store consumption and production data and the knowledge information created which can help both consumers and producers. Mobile devices and applications will help on the access to information.

## 6. FUTURE SCOPE

In future, we are planning to include some interesting features like solar-based system and battery voltage detectors to check the status of battery of vehicle. We are planning to link the RFID cards with user's prepaid bank account using various payment apps like paytm, google pay. These extra features make the system more accurate, reliable and user friendly.

## REFERENCES

- Electric Vehicles Charging Technology Review and Optimal Size Estimation, Published: 02 October 2020
- Smart Science volume 6 (2018), issue 1, A Comprehensive Review on Solar Powered Electric Vehicle Charging System by Saadullah khan, Aqueel Ahmad, Furkan Ahamd, Mahdi Shafaati Shemami, Mohammad saad Alam & Siddiq Khateeb , department of electrical engineering, Aligarah, India.
- Engineering Science and Technology, an International Journal 21 (2018). Review of static and dynamic wireless electric vehicle charging system by Chirag Panchal, Sascha Stegen, Junwei Lu Griffith School of Engineering, Griffith University, Nathan Campus, Brisbane 4111, Australia.
- Trivedi, N., Gujar, N. S., Sarkar, S., & Pundir, S. P. S. (2018). Different fast charging methods and topologies for EV charging. 2018 IEEMA Engineer Infinite Conference (eTechNxT). doi:10.1109/etechnxt.2018.8385313
- Chynoweth, J., Ching-Yen Chung, Qiu, C., Chu, P., & Gadh, R. (2014). Smart electric vehicle charging infrastructure overview. ISGT 2014. doi:10.1109/isgt.2014.6816440
- Dharmakeerthi, C. H., Mithulananthan, N., & Saha, T. K. (2013). Planning of electric vehicle charging infrastructure. 2013 IEEE Power & Energy Society General Meeting. doi:10.1109/pesmg.2013.6672085
- Links

- [https://en.wikipedia.org/wiki/Charging\\_station](https://en.wikipedia.org/wiki/Charging_station)
- <https://bit.ly/2NAmQRv>
- <https://whatis.techtarget.com/definition/electric-vehicle-charging-station>
- <https://www.slideshare.net/mobile/SarangBongirwar/charging-stations-for-electric-vehicle>