

Design and Analysis of a 4 Wheel Drive Transmission for BAJA SAE

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Abstract - An all-terrain vehicle (ATV) is engineered to navigate various surfaces and terrains, specifically designed to tackle challenging road conditions. Essential features of an ATV include high ground clearance and flexible suspension springs. The demand for a four-wheel-drive (4WD) transmission in lightweight ATVs is notably high due to its ability to enhance traction and augment off-road capabilities by distributing power across all four tires. This paper outlines a methodology focused on crafting and verifying a four-wheel driveline for a lightweight ATV, employing diverse modeling and simulation software tools. The integration of a Briggs and Stratton engine with a continuously variable transmission (CVT) allows seamless, infinite gear ratios within its predetermined range, ensuring smooth shifts. A two-stage reduction gearbox is utilized to amplify torque from the CVT, enhancing tire traction. Propelling power is transferred to the front differential through a propeller shaft, while a shifting mechanism facilitates the transition between two-wheel-drive (2WD) and 4WD modes. Detailed component designs are created using SolidWorks for iterative parameter adjustments. Additionally, the durability and material selection of driveline components are analyzed using Ansys software. The primary objective of this research paper is to establish a groundwork for future advancements in lightweight ATV driveline technology.

Key Words: All-terrain vehicle, Off-road, Four-wheel drive, CVT, Gearbox

1. INTRODUCTION

The heart of a power transmission system, a transmission ensures precise power delivery. In the realm of BAJA SAE [1], this system comprises the engine, gearbox, driveshaft, differential, and axles. Its core function lies in transforming higher engine speeds into slower wheel rotations, augmenting torque in the process.

Gearboxes are intricate assemblies of gears varying in size, tailored to meet specific torque demands dictated by road conditions, load factors, and terrains.

BAJA SAEINDIA stands as an intercollegiate engineering design competition aimed at undergraduate and graduate students in engineering disciplines. It mirrors real-world engineering challenges, demanding teams to conceive, engineer, construct, test, advocate, and compete with a vehicle, vying for acceptance by a fictitious manufacturing

firm. This multifaceted challenge necessitates teamwork, financial management, and a delicate balance with academic commitments.

2. METHODOLOGY

Considering all Baja competition events, the gearbox design prioritizes two crucial aspects: minimizing gearbox weight and ensuring the resilience of gear teeth. This approach unfolds in a systematic manner: Gear Ratio Calculation → Gear Design → Load Assessment on Gears → Material Selection for Gears → Gear Analysis → Determination of Factors crucial to Gear Performance.

2.1 Transmission Specifications

I. Engine (according to BAJA2021 Rulebook) [1]:

Engine: 19L232-0054-G1 (Briggs and Stratton).

Power: 10HP = 7.46 kW

Engine Torque (Te): 19.67 Nm.

Speed in rpm (N): 3800 rpm.

II. CVT: Customised JITRC1 [4]. CVT Ratio: 0.6 to 3.9

III. Diameter of Wheels: 0.558 m / 22 inch.

IV. Vehicle's Curb Weight: 220 kg.

V. Rolling Resistance (μ): 0.08

It varies based on road types and wheel design, with 0.08 being the universal maximum threshold.

VI. Transmission Efficiency (E): 75% (assumed, factoring in all losses).

3. GEAR SYSTEM CALCULATIONS

Maximum speed of vehicle is 60 Km/Hr as per the SAE BAJA 2021[1]. Based on a maximum torque of 500 Nm, our calculations suggest an optimal Gear Ratio of 8:1 for the two-stage Gearbox.

$$\text{Max Speed of Vehicles} = \frac{N \times C \times E \times 3.6}{CR \times GR \times 60}$$

CR is CVT Ratio, GR is Gear Ratio, E is efficiency of transmission, C is circumference of wheels.

$$60 = \frac{3800 \times 3.14 \times 0.558 \times 0.75 \times 3.6}{0.6 \times GR \times 60}$$

So, GR is 8.32

$$\text{Torque on wheels} = T_e \times CR \times GR \times E$$

$$500 = 19.67 \times 3.9 \times GR \times 0.75$$

So, GR is 8.690

To achieve high speed, a low gear ratio is necessary, while higher torque demands a higher gear ratio. Given the vehicle's speed limit of 60 km/hr[1], we determined an optimal gear ratio of 8:1 for peak performance in balancing speed and torque.

Gear type is Spur Gear, with gear ratio of 8:1 and the gearbox type is a 2 stage compound gearbox.

Table -1: Gear Values at different stages

First Stage	Pinion=21 Gear=67 Face width=20 mm Module=2	Gear Ratio=3.2
Second Stage	Pinion=30 Gear=7 Face width=25 mm Module=2.5	Gear Ratio=2.5
Bevels at Gearbox	Pinion=20 Gear=24 Face width=30 mm Module=3	Gear Ratio=1.2
Differential Pinion	Teeth=22 Face width=45 Module=3	Gear Ratio=2
Differential Crown	Teeth=44 Face width=45 Module=3	Gear Ratio=2

$$\text{First Stage Reduction} = \frac{\text{Number of teeth on gear}}{\text{Number of teeth on pinion}}$$

$$= \frac{67}{21} = 3.2$$

$$\text{Second Stage Reduction} = \frac{\text{Number of teeth on gear}}{\text{Number of teeth on pinion}}$$

$$= \frac{75}{30} = 2.5$$

$$\text{Total Reduction} = \text{First Stage} \times \text{Second Stage} = 8$$

Reduction at Sun and Planet is taken as 1:1.

Table -2: Final Gearbox Values

Type of Gearbox	2 Stage Gearbox
Type of Gear	Spur Gear
Gear Ratio	8:1
First Stage Reduction Ratio	3.2
Second Stage Reduction Ratio	2.5
Pressure angle (β)	20

4. DESIGN OF GEARS

$$\text{Pitch Circle Diameter (PCD)} = T_n \times M$$

Here, T_n represents the number of gear teeth, while M signifies the module.

For Stage 1,
 $PCD = 67 \times 2 = 134 \text{ mm}$

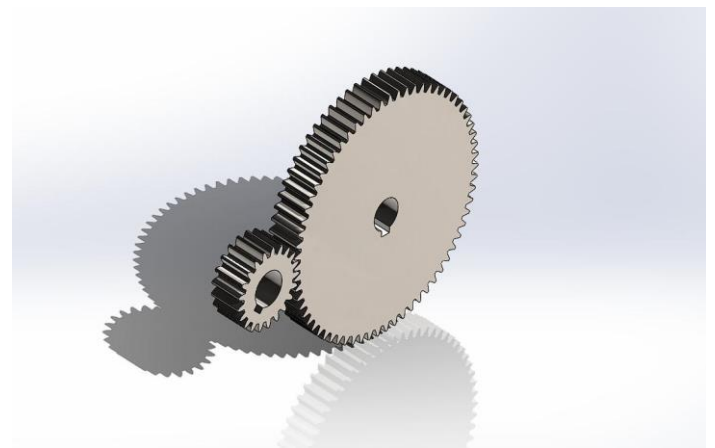


Fig -1: First Stage

For Stage 2,
 $PCD = 75 \times 2.5 = 187.5 \text{ mm}$

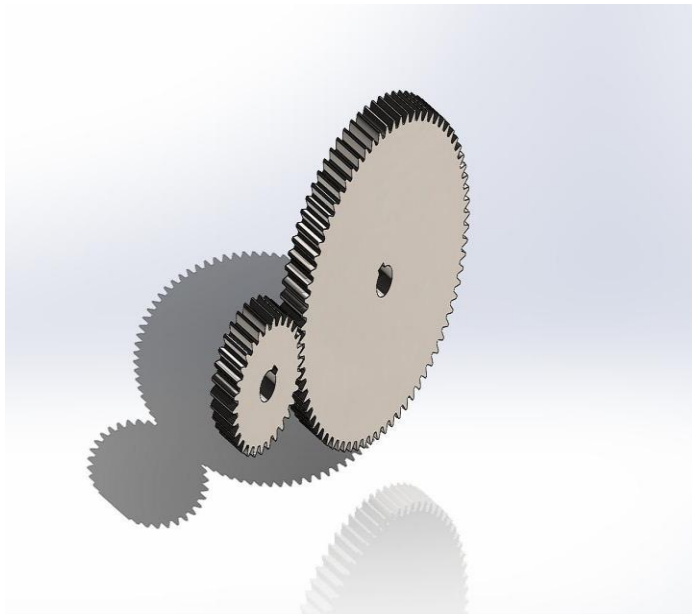


Fig -2: Second Stage

PCD for Bevel at Gearbox,
 $PCD = 24 \times 3 = 72 \text{ mm}$

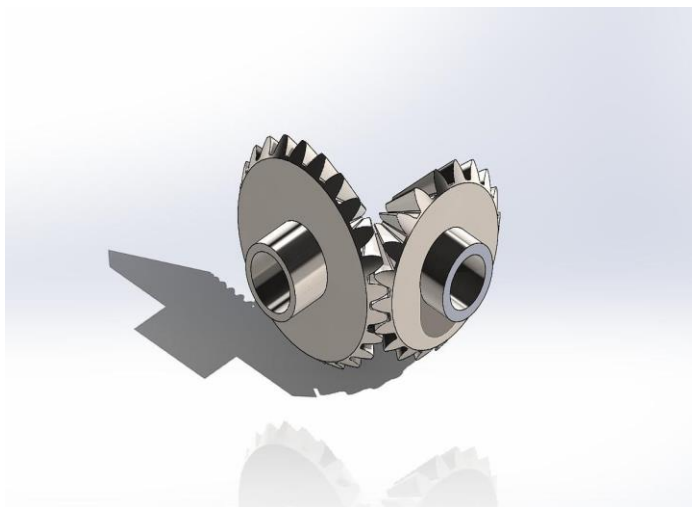


Fig -3: Bevel at Gearbox

For Differential Crown,
 $PCD = 44 \times 3 = 132 \text{ mm}$

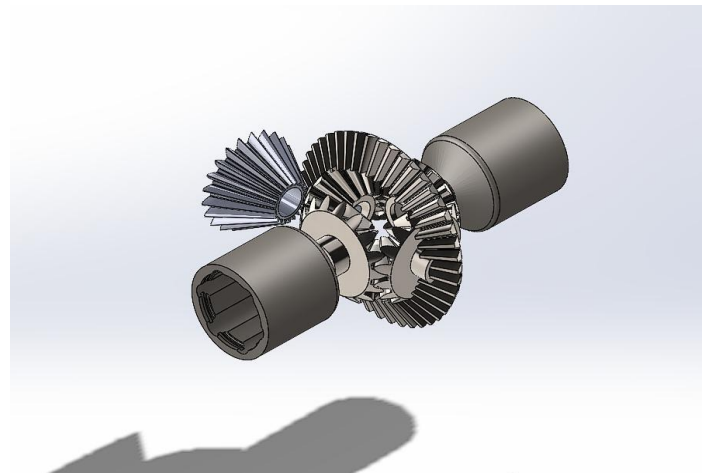


Fig -4: Differential Crown

5. CALCULATION OF LOADS ACTING ON GEARS

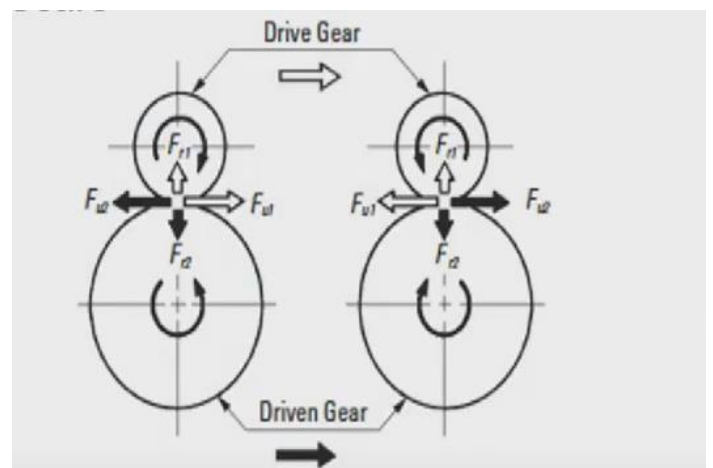


Fig -5: Forces Acting on Gears

For First Stage Gear,

$$(1) \text{ Tangential Forces } (F_t) = \frac{2000 \times T}{PCD}$$

T is maximum torque, which is calculated as
 $19.67 \times 3.9 = 76.71 \text{ NM}$.

$$F_t = \frac{2000 \times 76.71}{134} = 1144.92 \text{ N}$$

$$(2) \text{ Radial Forces } (F_r) = F_t \times \tan(\beta) \\ = 1144.92 \times \tan(20) = 412.17 \text{ N}$$

For Second Stage Gear,

$$(1) \text{ Tangential Forces } (F_t) = \frac{2000 \times T}{PCD}$$

T is maximum torque, which is calculated as
 $19.67 \times 3.9 = 76.71 \text{ NM}$.

$$F_t = \frac{2000 \times 76.71}{187.5} = 818.24 \text{ N}$$

(2) *Radial Forces (Fr)* = $F_t \times \tan(\beta)$
 = $818.24 \times \tan(20) = 294.56 \text{ N}$

Force of Bevel at Gearbox,

(1) *Tangential Force (Ft)* = $\frac{2000 \times T}{D_m}$

Where, D_m is the center reference diameter which is calculated as,

$$D_m = d - (b \times \sin(\delta))$$

b is Face width, (δ) is cone angle

$$(\delta) = \tan^{-1}\left(\frac{z_1}{z_2}\right)$$

z_1 is number of teeth on pinion, z_2 is number of teeth on gear.

$$= \tan^{-1}\left(\frac{20}{24}\right) = 39.7^\circ$$

$$D_m = 72 - (30 \times \sin(39.7)) = 53.1 \text{ mm}$$

$$F_t = \frac{2000 \times 76.71}{53.1} = 2894.71 \text{ N}$$

(2) *Radial Force (Fr)* = $F_t \times \tan(\beta) \times \cos(\delta)$
 = $2894.71 \times \tan(20) \times \cos(39.7) = 792 \text{ N}$

(3) *Axial Force (Fx)* = $F_t \times \tan(\beta) \times \sin(\delta)$
 = $2894.71 \times \tan(20) \times \sin(39.7) = 656.52 \text{ N}$

For Differential Crown,

(1) *Tangential Forces (Ft)* = $\frac{2000 \times T}{PCD}$

T is the maximum torque, which is calculated as $19.67 \times 3.9 = 76.71 \text{ NM}$

$$F_t = \frac{2000 \times 76.71}{132} = 1162.27 \text{ N}$$

(2) *Radial Force (Fr)* = $F_t \times \tan(\beta)$
 = $1162.27 \times \tan(20) = 418.41 \text{ N}$

6. GEAR MATERIAL SELECTIONS

Gear materials are selected based on loads acting on the gears in the endurance phase of the competition. The material should be low in cost and should be able to handle the maximum force acting. Gears should have a life expectancy of working through a complete season. Since the competition focuses on compactness and lesser weight of the ATV, the complete gearbox and differential should be compact and have as low weight as possible.

Table -3: Material Properties

	Gear Material	Gearbox Case Material
Material	EN19	Al 7075
Tensile Strength	655 MPA	572 MPA
Yield Strength	415 MPA	476 MPA
Young's Modulus	210 GPA	71.7 GPA
Poisson's Ratio	0.3	0.33

7. ANALYSIS OF GEARS

The analysis was conducted using ANSYS Workbench 19.2.

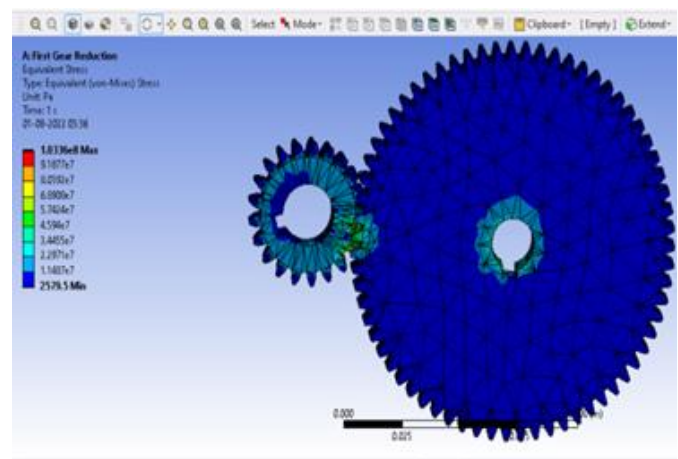


Fig -6: Stress Analysis of First Stage Gears

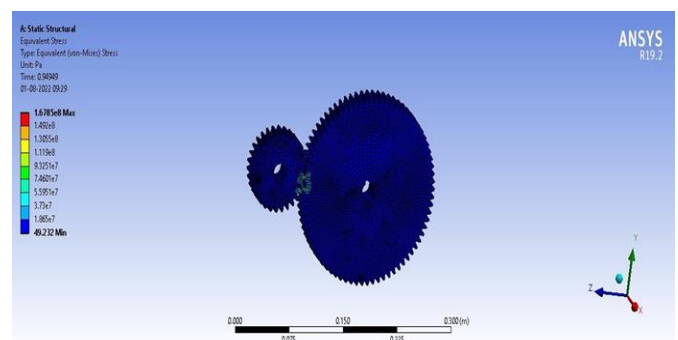


Fig -7: Stress Analysis of Second Stage Gears

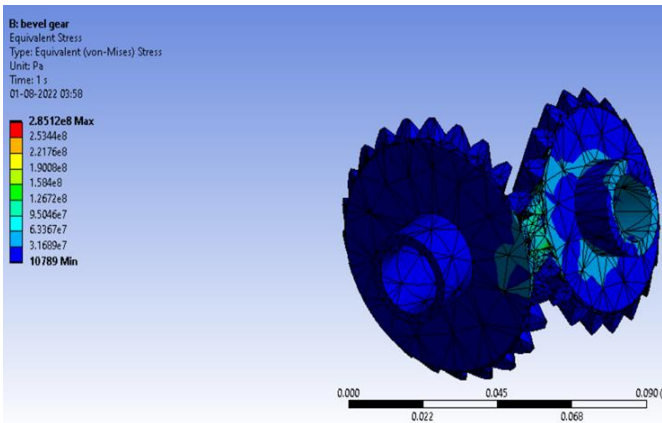


Fig -8: Stress Analysis of Bevel Gears

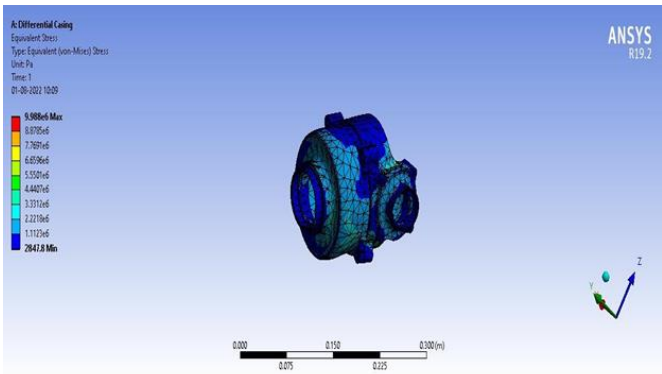


Fig -9: Stress Analysis of Differential Casing

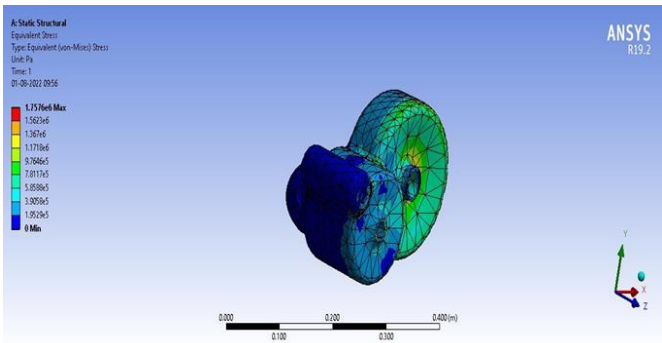


Fig -10: Stress Analysis of Gearbox Casing

8. CALCULATION OF FACTORS DEPENDING UPON THE GEARS

$$1. \text{ Max Speed of Vehicles} = \frac{N \times C \times E \times 3.6}{CR \times GR \times 60}$$

$$= \frac{3800 \times 3.14 \times 0.558 \times 0.75 \times 3.6}{0.6 \times 8 \times 60} = 62.41 \frac{Km}{Hr}$$

2. Acceleration

Tractive effort: Tractive effort refers to the force exerted at the driving wheel rims of a vehicle in motion, crucial for horizontal acceleration of the vehicle's mass[7].

$$\text{Tractive Effort (TE)} = \frac{Te \times CR \times GR \times E}{R}$$

$$= \frac{19.67 \times 3.9 \times 8 \times 0.75}{0.279} = 1649.74 \text{ N}$$

$$\text{Rolling Resistance (RR)} = W \times \mu$$

$$= 220 \times 9.81 \times 0.08 = 172.656 \text{ N}$$

$$\text{Total Resistance (TR)} = \text{Air Resistance (AR)} + \text{Rolling Resistance (RR)}$$

With the vehicle speed capped at 60 km/hr, negligible air resistance is anticipated.

$$TR = 0 + 172.656 = 172.656 \text{ N}$$

$$\text{Acceleration} = \frac{TE - TR}{m}$$

$$= \frac{1649.74 - 172.56}{220} = 6.71 \frac{m}{s^2}$$

Gradeability: It refers to the capability of a vehicle to climb or ascend inclines or slopes while maintaining performance and speed.

$$\text{Gradeability} = \frac{100 \times (TE - TR)}{W}$$

$$= \frac{100 \times (1649.74 - 0.08)}{220 \times 9.81} = 68.44 \%$$

$$3. \text{ Torque on wheels (TW)} = T \times CR \times GR \times E$$

$$= 19.67 \times 3.9 \times 8 \times 0.75 = 460.278 \text{ Nm}$$

Where,

- N: Engine Speed (rpm)
- C: Wheel Circumference (m)
- R: Wheel Radius (m)
- W: Vehicle Weight (N)
- m: Vehicle Mass (kg)
- E: Transmission Efficiency (%)
- CR: C.V.T Ratio
- GR: Gear Ratio
- T: Maximum Engine Torque (Nm)
- Te: Engine Torque (Nm)
- β: Pressure Angle

9. RESULT

After thorough design, analysis, and calculations, the following conclusions were drawn:

Table -4: Results

Material of Gears	EN19
Material of Gear Casing	Al 7075
Type of Gearbox	2 Stage Compound Gearbox
Overall Gear Reduction Ratio	8:1
First Stage Reduction Ratio	3.2
Second Stage Reduction Ratio	2.5
Differential Pinion and Crown Reduction Ratio	2
Bevels at Gearbox Reduction Ratio	1.2
Pressure Angle	20 Degree
No. of teeth in First Stage(Gear, Pinion)	67, 21
No. of teeth in Second Stage(Gear, Pinion)	75, 30
Max speed of vehicle	62.41 Km/Hr
Acceleration	6.71 m/s ²
Gradeability	68.44%
Torque on Wheels	460.278 Nm

10. CONCLUSION

The primary objective of this study was to meticulously design and analyze the transmission gearbox and differential for the SAE BAJA competition. This involved a comprehensive exploration of the forces impacting gears and gear reduction within the Machine Design course. Determination of overall gear ratios was crucial to achieving the desired speed and torque output.

Careful considerations such as gear material selection, teeth count, and gear type were made to mitigate potential failure risks. Detailed design analysis was conducted using ANSYS Workbench 19.0. Consequently, the transmission has undergone comprehensive optimization, ensuring its readiness to efficiently transmit the necessary speed and torque, enabling the vehicle to navigate all dynamic and endurance race obstacles in the SAE BAJA competition.

11. GALLERY

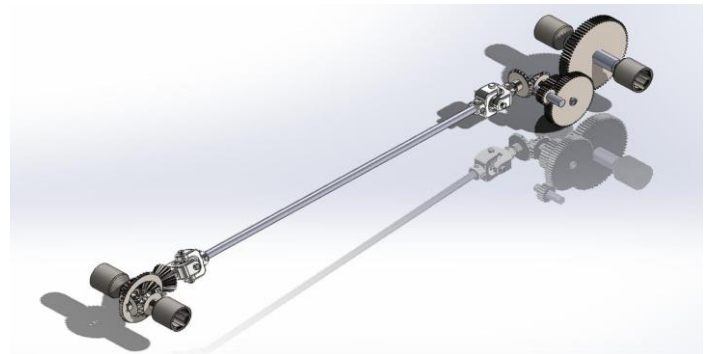


Fig -11: Complete Transmission Assembly

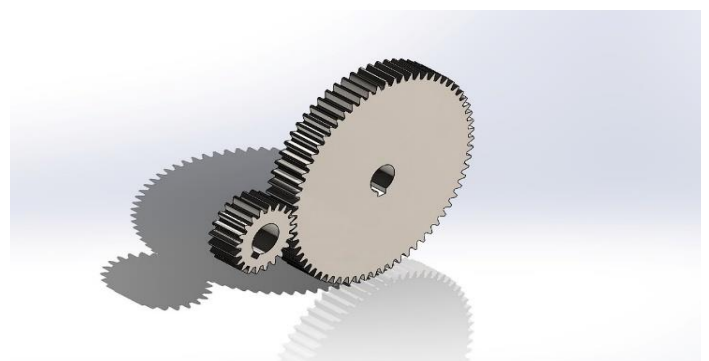


Fig -12: First Stage Reduction

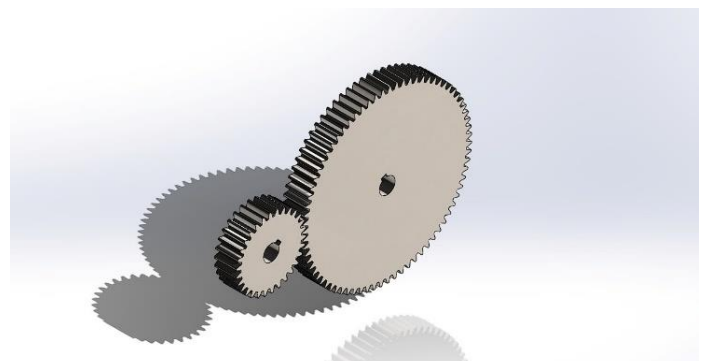


Fig -13: Second Stage Reduction

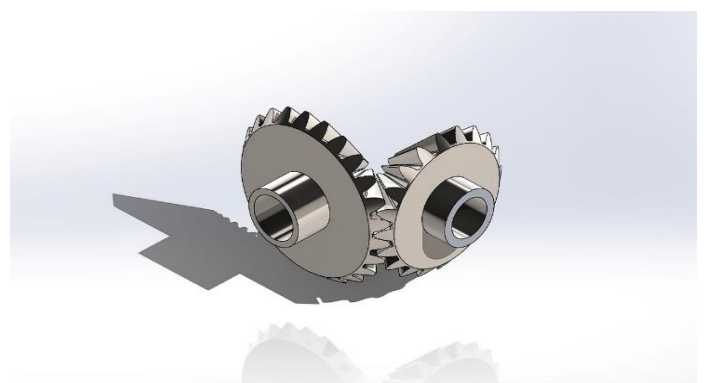


Fig -14: Bevels at Gearbox

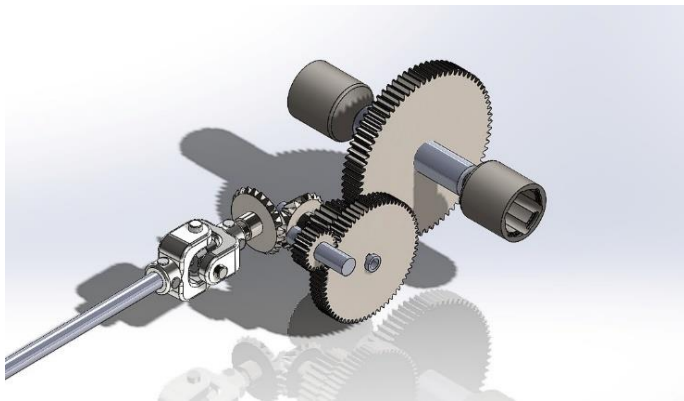


Fig -15: Gearbox Assembly

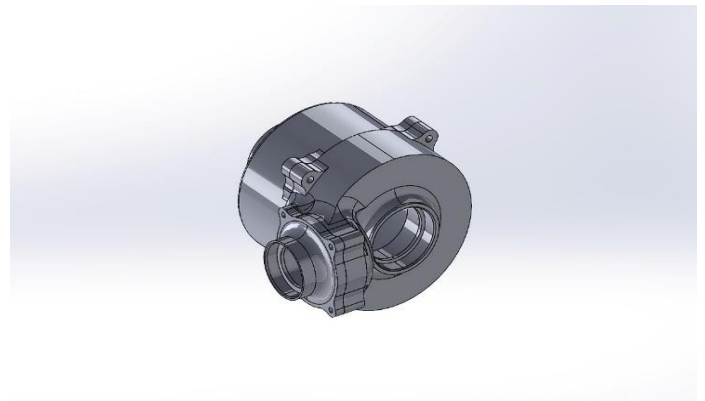


Fig -18: Differential Casing

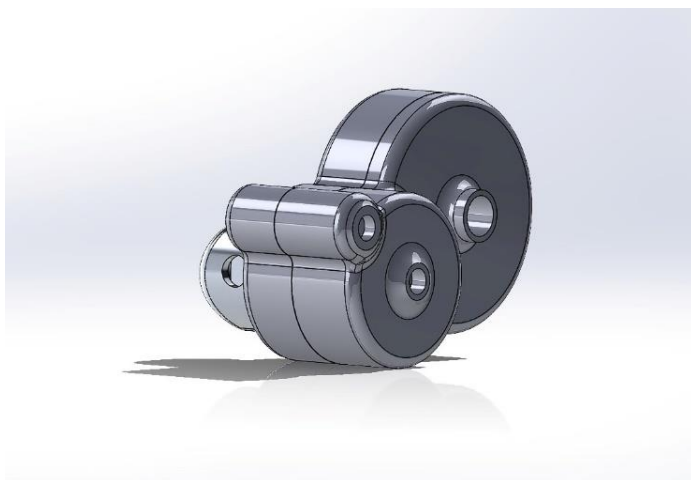


Fig -16: Gearbox Casing

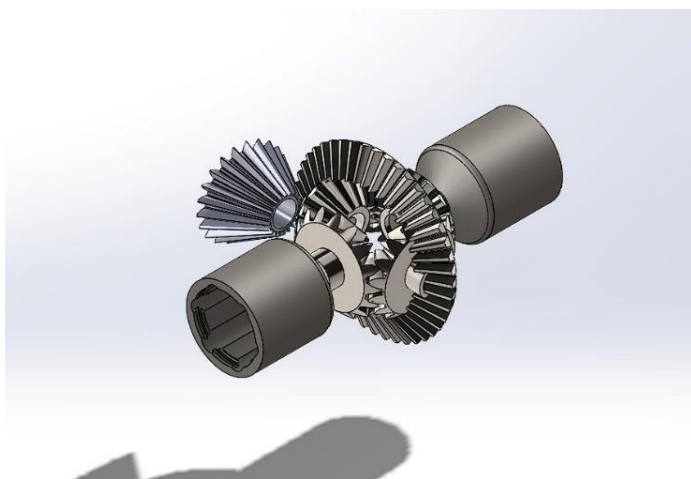


Fig -17: Differential Mechanism

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BIOGRAPHIES



"I am Ayub Ali Khan and I have done my graduation in BE in Manufacturing Processes and Automation Engineering from NSUT. I am from Delhi, India and have a keen interest in Design and Computer Aided Engineering."



"I am Nimanshu and I have done my graduation in BE in Manufacturing Processes and Automation Engineering from NSUT. I am from Delhi, India and my passion lies in Computer Aided Engineering and Aerodynamics."